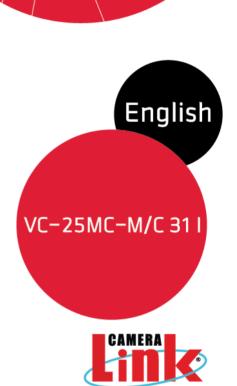
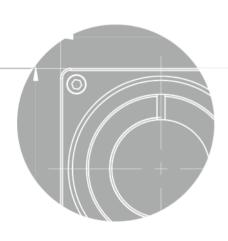


User Manual





VICWORKS

D-19-621



Revision History

Revision	Date	Description	
1.0	2019-08-30	nitial Release	
		Applied new CI	
1.1	2020-12-22	Added the Reverse Y feature	
		Added the Command List	

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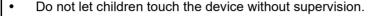
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1 Precautions

General

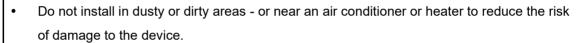
 Do not drop, disassemble, repair or alter the device. Doing so may damage the camera electronics and cause an electric shock.





- Stop using the device and contact the nearest dealer or manufacturer for technical assistance if liquid such as water, drinks or chemicals gets into the device.
- Do not touch the device with wet hands. Doing so may cause an electric shock.
- Make sure that the temperature of the camera does not exceed the temperature range specified in <u>5.2 Specifications</u>. Otherwise the device may be damaged by extreme temperatures.

Installation and Maintenance





- Avoid installing and operating in an extreme environment where vibration, heat, humidity, dust, strong magnetic fields, explosive/corrosive mists or gases are present.
- Do not apply excessive vibration and shock to the device. This may damage the device.
- Avoid direct exposure to a high intensity light source. This may damage the image sensor.
- Do not install the device under unstable lighting conditions. Severe lighting change will
 affect the quality of the image produced by the device.
- Do not use solvents or thinners to clean the surface of the device. This can damage the surface finish.

Power Supply



- Applying incorrect power can damage the camera. If the voltage applied to the camera is
 greater or less than the camera's nominal voltage, the camera may be damaged or
 operate erratically. Please refer to <u>5.2 Specifications</u> for the camera's nominal voltage.
 - X Vieworks Co., Ltd. does NOT provide power supplies with the device.
- Make sure the power is turned off before connecting the power cord to the camera.

 Otherwise damage to the camera may result.

2 Warranty

Do not open the housing of the camera. The warranty becomes void if the housing is opened. For information about the warranty, please contact your local dealer or factory representative.

3 Compliance & Certifications

3.1 FCC Compliance

This equipment has been tested and found to comply with the limits for a Class A digital device, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference when the equipment is operated in a commercial environment. This equipment generates, uses, and can radiate radio frequency energy and, if not installed and used in accordance with the instruction manual, may cause harmful interference to radio communications. Operation of this equipment in a residential area is likely to cause harmful interference in which case the user will be required to correct the interference at his own expenses.

3.2 CE: DoC

EMC Directive 2014/30/EU
EN 55032:2012 (Class A), EN 55024:2010
Class A

3.3 KC

KCC Statement

Туре	Description		
Class A	This device obtained EMC registration for office use (Class A), and may be		
(Broadcasting Communication	used in places other than home. Sellers and/or users need to take note of		
Device for Office Use)	this.		

4 Package Component

Package Component



VC-25MC-31 I

5 Product Specifications

5.1 Overview

The VC-25MC-31 I, the latest model of the industrial proven VC series, is a new 25 megapixel resolution CMOS camera with the Camera Link interface. The VC-25MC-31 I uses the latest CMOS global shutter image sensor (GMAX0505) technology from Gpixel and offers up to 31.7 frames per second at 5120 × 5120 resolution. These combinations of high resolution, high speed and global shutter set a new standard for industrial, scientific and surveillance digital imaging applications. Equipped with the Vieworks' innovative technologies proved by world's top FPD manufacturers, the VC-25MC-31 I camera offers not only highly uniformed images but also high speed image processing capabilities. Featured with high quality image uniformity and high resolution, this camera is ideal for wide range of demanding applications such as FPD, PCB and semiconductor inspections.

Main Features

- High Speed 25 Megapixel CMOS Image Sensor
- Electronic Exposure Time Control (Global Shutter)
- Output Pixel Format: 8 / 10 / 12 bit
- Line Output
- Camera Link Base / Medium / Full / 10 Tap
- Device Tap Geometry: 2 Tap, 4 Tap, 8 Tap, 10 Tap
- Gain / Black Level Control
- Test Pattern
- Temperature Monitor
- Field Upgrade
- DSNU and PRNU Correction
- Flat Field Correction
- GenlCam Compatible XML based Control

5.2 Specifications

The technical specifications of the VC-25MC-31 I camera are as follows.

Specifications		VC-25MC-M/C 31 I	
Active Image (H × V)		5120 × 5120	
Sensor		Gpixel GMAX0505	
Optical Format (Diagonal)	1.1" (18.1 mm)	
Pixel Siz	e	2.5 μm × 2.5 μm	
Interface	Э	Camera Link Base / Medium / Full / 10 Tap	
Electronic SI	nutter	Global Shutter	
		2 Tap: 6.4 fps	
May Frama	Data	4 Tap: 12.7 fps	
Max. Frame	Rate	8 Tap: 25.2 fps	
		10 Tap: 31.7 fps	
Pixel Data Format	Mono	Mono 8, Mono 10, Mono 12	
- Fixel Data Follilat	Color	GB Bayer 8, GB Bayer 10, GB Bayer 12	
Camera Link Pixel Clock		85 MHz	
Exposure Time		1 μs ~ 60 s (1 μs step)	
Partial Scan (Max. Speed)		546.4 fps at 64 × 2	
Black Level C	Control	0 ~ 255 LSB at 12 bit	
Gain Con	trol	1× ~ 32×	
Trigger Synchro	onization	Free-Run, Hardware Trigger or CC1	
External Tri	gger	3.3 V ~ 24.0 V, 10 mA, Logical level input, Optically isolated	
Software Tr	igger	Asynchronous, Programmable via Camera API	
Dynamic Ra	ange	65 dB	
Lens Mou	ınt	C-mount	
Power	External	11 ~ 24 V DC	
1 OW61	Dissipation	Typ. 6.0 W	
Temperati	ıre	Operating: 0 ∼ 40°C, Storage: -40°C ∼ 70°C	
Dimension / \	Veight	50 mm \times 50 mm \times 54 mm, 215g (with C-mount)	
Configuration SW		Configurator / Vieworks Imaging Solution 7.X	

Table 5.1 Specifications of VC-25MC-31 I

5.3 Camera Block Diagram

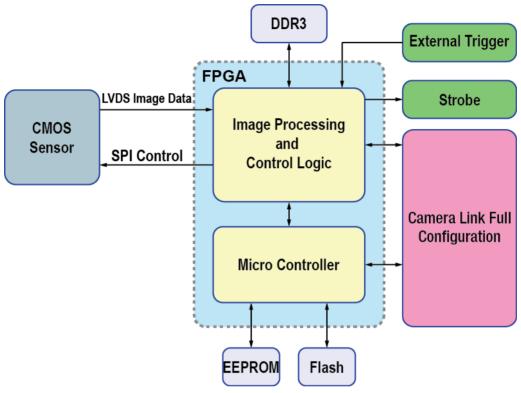


Figure 5.1 Camera Block Diagram

All controls and data processing of the VC-25MC-31 I camera are carried out in one FPGA chip. The FPGA generally consists of a 32-bit RISC Micro-Controller and Processing & Control logic. The Micro-Controller receives commands from the user through the Camera Link interface and then processes them. The Processing & Control logic processes the image data received from the CMOS image sensor and then transmits data through the Camera Link interface. The Processing & Control logic also controls time-sensitive trigger inputs and output signals. Furthermore, Flash and DDR3 are installed outside FPGA. The DDR3 is used for the frame buffer to process images and the Flash stores the firmware to operate the Micro-Controller.

5.4 Spectral Response

The following graphs show the spectral response of the VC-25MC-31 I color and monochrome cameras.

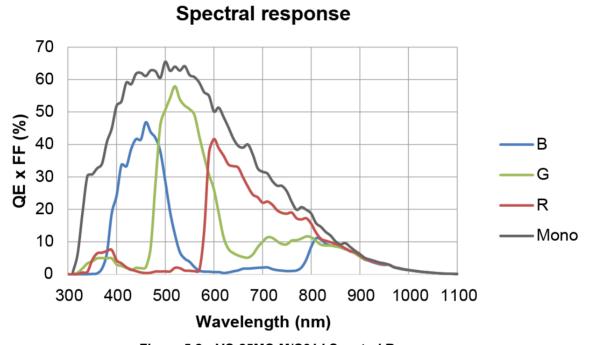
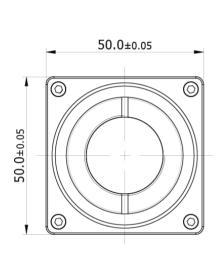
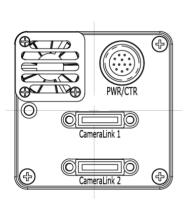


Figure 5.2 VC-25MC-M/C31 I Spectral Response

5.5 Mechanical Specification

The camera dimensions in millimeters are shown in the following figure.





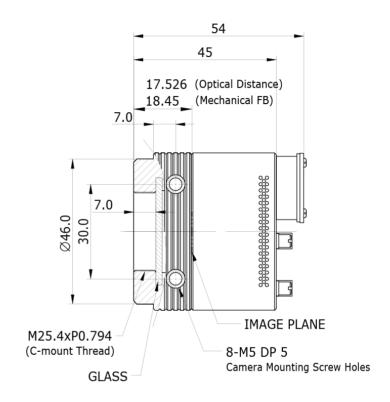


Figure 5.3 VC-25MC-31 I C-mount Mechanical Dimension



6 Connecting the Camera

The following instructions assume that you have installed a Camera Link frame grabber in your computer including related software. For more information, refer to your Camera Link frame grabber user manual. To connect the camera to your computer, follow the steps below:

- 1. Make sure that the power supply is not connected to the camera and your computer is turned off.
- 2. Plug one end of a Camera Link cable into the Camera Link1 connector on the camera and the other end of the Camera Link cable into the Base connector on the Camera Link frame grabber.
- Plug one end of the other Camera Link cable into the Camera Link2 connector on the camera and the other end of the Camera Link cable into the Medium/Full connector on the Camera Link frame grabber.
- 4. Connect the plug of the power adapter to the power input receptacle on the camera.
- 5. Plug the power adapter into a working electrical outlet.
- 6. Verify all the cable connections are secure.

Precautions for using Camera Link Medium / Full / 10 Tap Configuration



The VC-25MC-31 I camera supports the Camera Link Base / Medium / Full / 10 Tap configuration. To operate the camera in the medium, full or 10 tap configuration, you must connect the camera to the Camera Link frame grabber using two Camera Link cables. Make sure that you connect both Camera Link1 (Base) and Camera Link2 (Medium/Full) connectors on the camera to their respective connectors on the Camera Link frame grabber.

6.1 Precaution about Blurring Compared to the Center

- Users do not need to adjust the tilt as it is adjusted as factory default settings.
- If the tilt settings need to be adjusted inevitably, please contact your local dealer or factory representative for technical support.

6.2 Controlling the Camera

- You can control the camera by using the Configurator.
- You can download the latest Configurator at http://www.vieworks.com.
- Please refer to your Camera Link frame grabber user manual.

Camera Interface

7.1 **General Description**

As shown in the following figure, three types of connectors and an LED indicator are located on the back of the camera and have the functions as follows:

1 12-pin Power Input and Control I/O Receptacle:

supplies power to the camera and can be set to operate as an input and output line.

② Status LED:

displays power status and operation mode.

3 26 pin SDR Connector 1 (Camera Link Base):

transmits video data and controls the camera.

(4) 26 pin SDR Connector 2 (Camera Link Medium/Full): transmits video data.

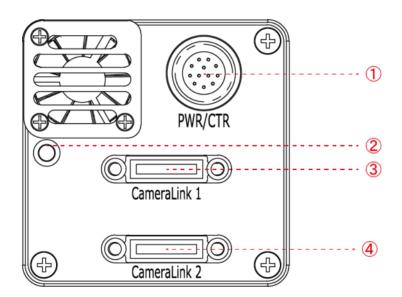


Figure 7.1 VC-25MC-31 I Back Panel

Camera Link SDR Connector 7.2

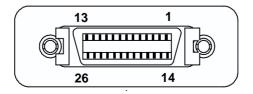


Figure 7.2 Camera Link Connector



The Camera Link connectors on the camera comply with the Camera Link standard and the following lists show the pin assignments of the connectors.

PAIR List	Pin	Signal Name	Туре	Description
DAID O	1	Ground	Ground	Cable Shield
PAIR 0	14	Ground	Ground	Cable Shield
DAID 4	2	-X0	LVDS - Out	Camera Link Transmitter
PAIR 1	15	+X0	LVDS - Out	Camera Link Transmitter
PAIR 2	3	-X1	LVDS - Out	Camera Link Transmitter
PAIR 2	16	+X1	LVDS - Out	Camera Link Transmitter
PAIR 3	4	-X2	LVDS - Out	Camera Link Transmitter
PAIR 3	17	+X2	LVDS - Out	Camera Link Transmitter
PAIR 4	5	-XCLK	LVDS - Out	Camera Link Transmitter
PAIR 4	18	+XCLK	LVDS - Out	Camera Link Transmitter
DAID 5	6	-X3	LVDS - Out	Camera Link Transmitter
PAIR 5	19	+X3	LVDS - Out	Camera Link Transmitter
PAIR 6	7	+ SerTC	LVDS - In	Serial Data Receiver
PAIR 0	20	- SerTC	LVDS - In	Serial Data Receiver
PAIR 7	8	- SerTFG	LVDS - Out	Serial Data Transmitter
PAIR /	21	+ SerTFG	LVDS - Out	Serial Data Transmitter
PAIR 8	9	- CC 1	LVDS - In	Software External Trigger
PAIR O	22	+ CC 1	LVDS - In	Software External Trigger
PAIR 9	10	N/C	N/C	N/C
PAIR 9	23	N/C	N/C	N/C
PAIR 10	11	N/C	N/C	N/C
PAIR 10	24	N/C	N/C	N/C
PAIR 11	12	N/C	N/C	N/C
PAIK II	25	N/C	N/C	N/C
DAID 10	13	Ground	Ground	Cable Shield
PAIR 12	26	Ground	Ground	Cable Shield

Table 7.1 Pin Assignments for Camera Link Connector 1



PAIR List	Pin	Signal Name	Туре	Description
DAID O	1	Ground	Ground	Cable Shield
PAIR 0	14	Ground	Ground	Cable Shield
PAIR 1	2	-Y0	LVDS - Out	Camera Link Transmitter
PAIR	15	+Y0	LVDS - Out	Camera Link Transmitter
PAIR 2	3	-Y1	LVDS - Out	Camera Link Transmitter
PAIR 2	16	+Y1	LVDS - Out	Camera Link Transmitter
DAID 2	4	-Y2	LVDS - Out	Camera Link Transmitter
PAIR 3	17	+Y2	LVDS - Out	Camera Link Transmitter
PAIR 4	5	-YCLK	LVDS - Out	Camera Link Transmitter
PAIR 4	18	+YCLK	LVDS - Out	Camera Link Clock Tx
DAID E	6	-Y3	LVDS - Out	Camera Link Channel Tx
PAIR 5	19	+Y3	LVDS - Out	Camera Link Channel Tx
PAIR 6	7	-	Not Used	Connected with 100 ohm
PAIR 0	20	-	Not Used	Connected with 100 onin
PAIR 7	8	-Z0	LVDS - Out	Camera Link Transmitter
PAIR /	21	+Z0	LVDS - Out	Camera Link Transmitter
DAID 0	9	-Z1	LVDS - Out	Camera Link Transmitter
PAIR 8	22	+Z1	LVDS - Out	Camera Link Transmitter
PAIR 9	10	-Z2	LVDS - Out	Camera Link Transmitter
PAIR 9	23	+Z2	LVDS - Out	Camera Link Transmitter
DAID 40	11	-ZCLK	LVDS - Out	Camera Link Transmitter
PAIR 10	24	+ZCLK	LVDS - Out	Camera Link Clock Tx
DAID 44	12	-Z3	LVDS - Out	Camera Link Channel Tx
PAIR 11	25	+Z3	LVDS - Out	Camera Link Channel Tx
DAID 40	13	Ground	Ground	Cable Shield
PAIR 12	26	Ground	Ground	Cable Shield

Table 7.2 Pin Assignments for Camera Link Connector 2

Model	Device Tap Geometry	CL Configuration	CL Connector 1	CL Connector 2
VC-25MC-31 I	2 Tap	BASE	0	X
	4 Tap	MEDIUM	0	0
	8 Тар	FULL	0	0
	10 Tap	10 Tap	0	0

Table 7.3 Connector Arrangement for the Device Tap Geometry



When you connect a Camera Link frame grabber to the Camera Link connectors on the camera using Camera Link cables, make sure you connect the cables to their correct connectors. If you connect the Camera Link connector 1 on the camera to a connector other than connector 1 of the Camera Link frame grabber, the camera may not transmit images correctly or the serial communication between the camera and the computer may fail.

7.3 Power Input and Control I/O Receptacle

The power input and control I/O receptacle is a 12-pin connector (part # HR10A-10R-12PB). The pin assignments and configurations are as follows:



Figure 7.3 Pin Assignments for Power Input and Control I/O Receptacle

Pin Number	Signal	Туре	Description
1	DC Ground	Input	Camera Power GND
2	+12 V DC	Input	Camera Power +12V DC
3	I/O Output -	Output	-
4	I/O Output +	Output	-
5	Trigger Input -	Input	-
6	Trigger Input +	Input	-
7 - 12	N/C	-	-

Table 7.4 Pin Configurations for Power Input and Control I/O Receptacle



- A recommended mating connector for the Hirose 12-pin connector is the Hirose 12-pin plug (part # HR10A-10P-12S) or the equivalent.
- It is recommended that you use the power adapter, which has at least 3 A current output at 11 24 V voltage output (You need to purchase a power adapter separately.).

Precaution for Power Input



- Make sure the power is turned off before connecting the power cord to the camera.
 Otherwise, damage to the camera may result.
- If the voltage applied to the camera is greater than specified in the specifications, damage to the camera may result.

7.4 Input Circuit

The following figure shows trigger signal input circuit of the 12-pin connector. Transmitted trigger signal is applied to the internal circuit through a photo coupler. With the Debounce feature, you can specify the width of input signal to be considered as a valid input signal. An external trigger circuit example is shown below.

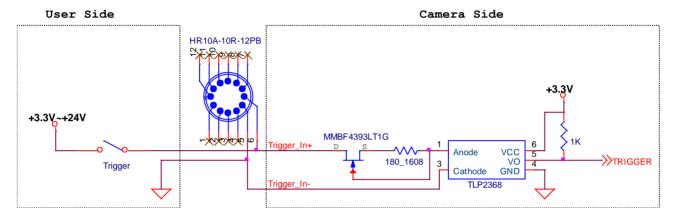


Figure 7.4 Input Schematic

7.5 Output Circuit

The following figure shows output circuit of the 12-pin connector. You can configure the output line by setting the Digital I/O Control (refer to 9.12 Digital I/O Control).

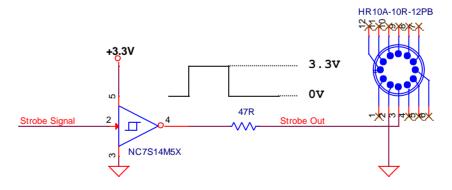


Figure 7.5 Output Schematic

8 Acquisition Control

This chapter provides detailed information about controlling image acquisition.

- Triggering image acquisition
- Setting the exposure time
- · Controlling the camera's image acquisition rate
- · Variation of the camera's maximum allowed image acquisition rate according to the camera settings

8.1 Overview

This section presents an overview of the elements involved with controlling the acquisition of images.

Three major elements are involved in controlling the acquisition of images.

- Acquisition Start and Acquisition Stop commands and the Acquisition Mode parameter
- Exposure start trigger
- Exposure time control



When reading the explanations in the overview and in this entire chapter, keep in mind that the term **frame** is typically used to mean a single acquired image.

Acquisition Start and Stop Commands and Acquisition Mode

The **Acquisition Start** command prepares the camera to acquire frames. The camera cannot acquire frames unless an **Acquisition Start** command has first been executed.

A parameter called the **Acquisition Mode** has a direct bearing on how the **Acquisition Start** command operates. The VC-25MC-31 I camera only supports **Continuous** for the **Acquisition Mode** parameter. If the **Acquisition Mode** parameter is set to **Continuous**, an **Acquisition Start** command does not expire after a single frame is acquired. Once an **Acquisition Start** command has been executed, you can acquire as many frames as you like. The **Acquisition Start** command will remain in effect until you execute an **Acquisition Stop** command. Once an **Acquisition Stop** command has been executed, the camera will not be able to acquire frames until a new **Acquisition Start** command is executed.



Exposure Start Trigger

Applying an exposure start trigger signal to the camera will exit the camera from the *waiting for exposure start trigger* acquisition status and will begin the process of exposing and reading out a frame (see Figure 8.1). As soon as the camera is ready to accept another exposure start trigger signal, it will return to the *waiting for exposure start trigger* acquisition status. A new exposure start trigger signal can then be applied to the camera to begin another frame exposure. The exposure start trigger has two modes: off and on.

If the **Trigger Mode** parameter is set to **Off**, the camera will generate all required exposure start trigger signals internally, and you do not need to apply exposure start trigger signals to the camera. The rate at which the camera will generate the signals and acquire frames will be determined by the way that you set several frame rate related parameters.

If the **Trigger Mode** parameter is set to **On**, you must trigger exposure start by applying exposure start trigger signals to the camera. Each time a trigger signal is applied, the camera will begin a frame exposure. When exposure start is being triggered in this manner, it is important that you do not attempt to trigger frames at a rate that is greater than the maximum allowed (There is a detailed explanation about the maximum allowed frame rate at the end of this chapter.). Exposure start trigger signals applied to the camera when it is not in a *waiting for exposure start trigger* acquisition status will be ignored.

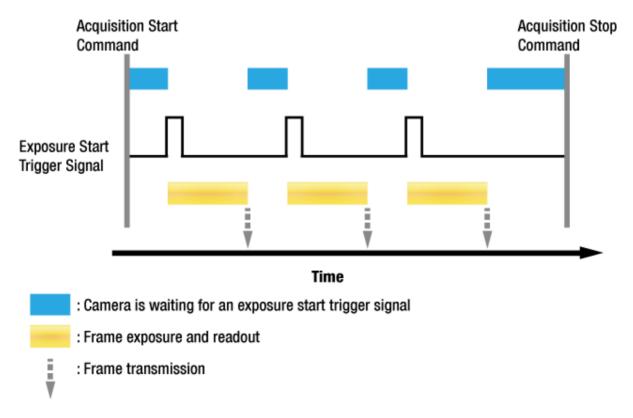


Figure 8.1 Exposure Start Triggering



Applying Trigger Signals

The paragraphs above mention "applying a trigger signal". There are three ways to apply an exposure start trigger signal to the camera: via **User Output0**, via **CC1** or via **Line0** (commonly referred to a hardware). To apply trigger signals via **User Output0**, you must set the **Trigger Source** parameter to **User Output0**. At that point, you can apply an exposure start trigger signal to the camera by switching the **User Output Value** parameter between **On** (rise) and **Off** (fall).

To apply trigger signals via Camera Link frame grabber, you must set the **Trigger Source** parameter to **CC1**. At that point, each time an externally generated electrical signal is applied to the camera by using the APIs provided by a Camera Link frame grabber manufacturer, the exposure start trigger signal will be applied to the camera. For more information, refer to your Camera Link frame grabber user manual.

To apply trigger signals via hardware (external), you must set the **Trigger Source** parameter to **Line0**. At that point, each time a proper electrical signal is applied to the camera, an occurrence of the exposure start trigger signal will be recognized by the camera.

Exposure Time Control

the frame acquisition.

When an exposure start trigger signal is applied to the camera, the camera will begin to acquire a frame.

A critical aspect of frame acquisition is how long the pixels in the camera's sensor will be exposed to light during

If the **Trigger Source** parameter is set to **User Output0**, **CC1** or **Line0**, there are two modes of operation: **Timed** and **Trigger Width**.

With the **Timed** mode, the **Exposure Time** parameter will determine the exposure time for each frame.

With the **Trigger Width** mode, the way that you manipulate the rise and fall of the User Output, CC1 or hardware (external) signal will determine the exposure time. The **Trigger Width** mode is especially useful if you want to change the exposure time from frame to frame.

8.2 Acquisition Start/Stop Commands and Acquisition Mode

Executing an **Acquisition Start** command prepares the camera to acquire frame. You must execute an **Acquisition Start** command before you can begin acquiring frames.

Executing an **Acquisition Stop** command terminates the camera's ability to acquire frames.

When the camera receives an **Acquisition Stop** command:

- If the camera is not in the process of acquiring a frame, its ability to acquire frames will be terminated immediately.
- If the camera is in the process of acquiring a frame, the frame acquisition process will be allowed to finish and the camera's ability to acquire new frames will be terminated.

The **Acquisition Status** parameter allows you to check whether the camera is in the process of acquiring a frame or not. When you read the **Acquisition Status** parameter while the camera is in the process of acquiring a frame, it will return True or the check box will be selected. When you read the **Acquisition Status** parameter while the camera is not in the process of acquiring a frame, it will return False or the check box will not be selected.



When you execute the **Acquisition Start** command while the previous frame acquisition process is still in progress, the command will be ignored. To avoid this, you must wait until the camera completes the frame acquisition process after the execution of the **Acquisition Stop** command. Then, you can safely execute the **Acquisition Start** command again.

The VC-25MC-31 I camera only provides the **Continuous** mode of operation for the **Acquisition Mode**. After an **Acquisition Start** command has been executed, exposure start can be triggered as desired. Each time an exposure start trigger is applied while the camera is in a *waiting for exposure start trigger* acquisition status, the camera will acquire and transmit a frame. The camera will retain the ability to acquire frames until an **Acquisition Stop** command is executed. Once the **Acquisition Stop** command is received, the camera will no longer be able to acquire frames.

8.3 Exposure Start Trigger

The **Trigger Selector** parameter is used to select a type of trigger and only the **Exposure Start** trigger is available on the VC-25MC-31 I camera. The Exposure Start trigger is used to begin frame acquisition. Exposure start trigger signals can be generated within the camera or may be applied externally by setting the **Trigger Source** parameter to **User Output0**, **CC1** or **Line0**. If an exposure start trigger signal is applied to the camera, the camera will begin to expose a frame.

8.3.1 Trigger Mode

The main parameter associated with the exposure start trigger is the **Trigger Mode** parameter.

The **Trigger Mode** parameter for the exposure start trigger has two available settings: **Off** and **On**.

8.3.1.1 Trigger Mode = Off

When the **Trigger Mode** parameter is set to **Off**, the camera will generate all required exposure start trigger signals internally, and you do not need to apply exposure start trigger signals to the camera.

If the **Trigger Mode** parameter is set to **Off**, the camera will automatically begin generating exposure start trigger signals when it receives an **Acquisition Start** command. The camera will continue to generate exposure start trigger signals until it receives an **Acquisition Stop** command.



Free Run

When you set the **Trigger Mode** parameter to **Off**, the camera will generate all required trigger signals internally. When the camera is set this way, it will constantly acquire images without any need for triggering by the user. This use case commonly referred as "free run".

The rate at which the exposure start trigger signals are generated may be determined by the camera's **Acquisition Frame Rate** parameter.

- If the parameter is set to a value less than the maximum allowed frame rate with the current camera settings, the camera will generate exposure start trigger signals at the rate specified by the parameter setting.
- If the parameter is set to a value greater than the maximum allowed frame rate with the current camera settings, the camera will generate exposure start trigger signals at the maximum allowed frame rate.

Exposure Time Control with Trigger Mode = Off

When the **Trigger Mode** parameter is set to **Off**, the exposure time for each frame acquisition is determined by the value of the camera's **Exposure Time** parameter. For more information about the Exposure Time parameter, see <u>8.4 Setting the Exposure Time</u>.



8.3.1.2 Trigger Mode = On

When the **Trigger Mode** parameter is set to **On**, you must apply an exposure start trigger signal to the camera each time you want to begin a frame acquisition. The **Trigger Source** parameter specifies the source signal that will act as the exposure start trigger signal.

The available settings for the **Trigger Source** parameter are:

- User Output0: You can apply an exposure start trigger signal to the camera by switching the User Output

 Value parameter between On and Off on your computer.
- **CC1**: You can apply an exposure start trigger signal to the camera via CC1 in the Camera Link interface. For more information, refer to your Camera Link frame grabber user manual.
- Line0: You can apply an exposure start trigger signal to the camera by injecting an externally generated electrical signal (commonly referred to as a hardware or external trigger signal) into the Power Input and Control I/O receptacle on the camera.
 Refer to 7.4 Input Circuit for more information.
- Timer0Active: You can apply an exposure start trigger signal to the camera using a user defined Timer signal. When you set the Timer Trigger Source parameter to Line0 in the Counter And Timer Control category, you can specify a delay for the Line0 signal by using the Timer Delay parameter. For more information, refer to 9.13 Timer Control.

You must also set the **Trigger Activation** parameter after setting the **Trigger Source** parameter.

The available settings for the **Trigger Activation** parameter are:

- Falling Edge: Specifies that a falling edge of the electrical signal will act as the exposure start trigger.
- Rising Edge: Specifies that a rising edge of the electrical signal will act as the exposure start trigger.



Exposure Time Control with Trigger Mode = On

When the **Trigger Mode** parameter is set to **On** and the **Trigger Source** parameter is set to **CC1** or **Line0**, the exposure time for each frame acquisition will be determined by the **Exposure Mode** parameter settings as follows:

• Exposure Mode = Timed: Exposure time can be controlled with the Exposure Time parameter.

• Exposure Mode = Trigger Width: Exposure time can be controlled by manipulating the external trigger

signal.

When the **Trigger Mode** parameter is set to **On** and the **Trigger Source** parameter is set to **User Output0**, the exposure time for each frame acquisition will be determined by the **Exposure Mode** parameter settings as follows:

Exposure Mode = Timed: Exposure time can be controlled with the Exposure Time parameter.

• Exposure Mode = Trigger Width: Exposure time can be controlled by switching the User Output Value

parameter between **On** and **Off**.



8.3.2 Using a CC1 Trigger Signal

If the **Trigger Mode** parameter is set to **On** and the **Trigger Source** parameter is set to **CC1**, you must apply a CC1 trigger signal to the camera to begin each frame acquisition. A CC1 trigger signal will act as the exposure start trigger signal for the camera. For more information, refer to your Camera Link frame grabber user manual. A rising edge or a falling edge of the CC1 signal can be used to trigger frame acquisition. The **Trigger Activation** parameter is used to select rising edge or falling edge triggering.

Assuming that the camera is in a *waiting for exposure start trigger* acquisition status, frame acquisition will start whenever the appropriate edge transition is received by the camera.

When the camera receives a CC1 trigger signal and begins exposure, it will exit the *waiting for exposure start trigger* acquisition status because at that point, it cannot react to a new exposure start trigger signal.

As soon as the camera is capable of reacting to a new exposure start trigger signal, it will automatically return to the *waiting for exposure start trigger* acquisition status.

When the camera is operating under control of a CC1 signal, the period of the CC1 trigger signal will determine the rate at which the camera is acquiring frames:

For example, if you are operating a camera with a CC1 trigger signal period of 500 $\,$ ms (0.5 s): So in this case, the frame rate is 2 fps.



8.3.3 Using an External Trigger Signal

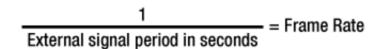
If the **Trigger Mode** parameter is set to **On** and the **Trigger Source** parameter is set to **Line0**, an externally generated electrical signal injected into the Power Input and Control I/O receptacle will act as the exposure start trigger signal for the camera. This type of trigger signal is generally referred to as a hardware trigger signal. A rising edge or a falling edge of the external signal can be used to trigger frame acquisition. The **Trigger Activation** parameter is used to select rising edge or falling edge triggering.

Assuming that the camera is in a *waiting for exposure start trigger* acquisition status, frame acquisition will start whenever the appropriate edge transition is received by the camera.

When the camera receives an external trigger signal and begins exposure, it will exit the *waiting for exposure* start trigger acquisition status because at that point, it cannot react to a new exposure start trigger signal.

As soon as the camera is capable of reacting to a new exposure start trigger signal, it will automatically return to the *waiting for exposure start trigger* acquisition status.

When the camera is operating under control of an external signal, the period of the external trigger signal will determine the rate at which the camera is acquiring frames:



For example, if you are operating a camera with an External trigger signal period of 500 $\,$ ms (0.5 s): So in this case, the frame rate is 2 fps.

8.3.3.1 External Trigger Delay

When you set the **Trigger Source** parameter to **Timer0Active**, you can specify a delay between the receipt of a hardware trigger signal and when the trigger becomes effective.

- 1. Set the Timer Trigger Source parameter in the Counter And Timer Control category to Line0.
- 2. Set the **Timer Delay** parameter to the desired Timer delay in microseconds.
- 3. Set the Trigger Source parameter in the Acquisition Control category to Timer0Active.
- 4. Execute the **Acquisition Start** command and inject an externally generated electrical signal into the Power Input and Control I/O receptacle. Then, the delay set by the **Timer Delay** parameter expires and the exposure for image acquisition begins.

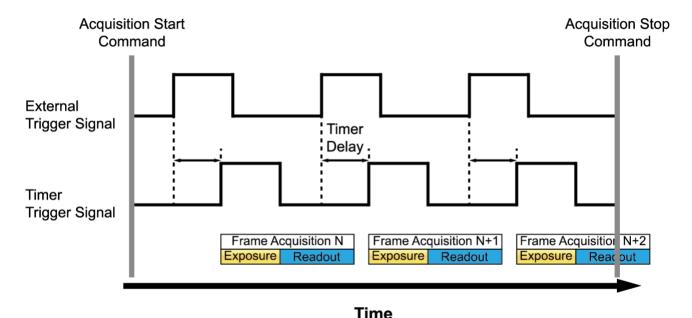


Figure 8.2 External Trigger Delay

8.3.4 Exposure Mode

If you are triggering the start of frame acquisition with an externally (CC1 or External) generated trigger signal, two exposure modes are available: **Timed** and **Trigger Width**.

Timed Exposure Mode

When the **Timed** mode is selected, the exposure time for each frame acquisition is determined by the value of the camera's **Exposure Time** parameter. If the camera is set for rising edge triggering, the exposure time starts when the external trigger signal rises. If the camera is set for falling edge triggering, the exposure time starts when the external trigger signal falls. The following figure illustrates **Timed** exposure with the camera set for rising edge triggering.

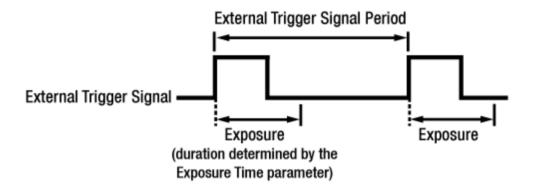


Figure 8.3 Timed Exposure Mode

Note that if you attempt to trigger a new exposure start while the previous exposure is still in progress, the trigger signal will be ignored.

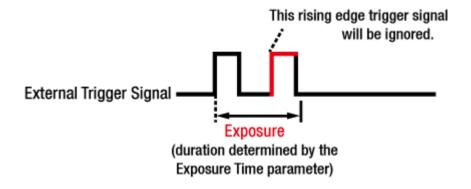


Figure 8.4 Trigger Overlapped with Timed Exposure Mode



Trigger Width Exposure Mode

When the **Trigger Width** exposure mode is selected, the length of the exposure for each frame acquisition will be directly controlled by the external trigger signal (CC1 or External). If the camera is set for rising edge triggering, the exposure time begins when the external trigger signal rises and continues until the external trigger signal falls. If the camera is set for falling edge triggering, the exposure time begins when the external trigger signal falls and continues until the external trigger signal rises. The following figure illustrates **Trigger Width** exposure with the camera set for rising edge triggering.

Trigger Width exposure is especially useful if you intend to vary the length of the exposure time for each frame.

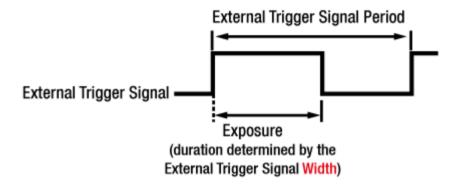


Figure 8.5 Trigger Width Exposure Mode

8.4 Setting the Exposure Time

This section describes how the exposure time can be adjusted manually by setting the value of the **Exposure**Time parameter. If you are operating the camera in any one of the following ways, you must specify an exposure time by setting the camera's **Exposure Time** parameter.

- the Trigger Mode is set to Off.
- the **Trigger Mode** is set to **On**, the **Trigger Source** is set to **CC1** or **Line0**, and the **Exposure Mode** is set to **Timed**.

The **Exposure Time** parameter must not be set below a minimum specified value. The **Exposure Time** parameter sets the exposure time in microseconds (μ s). The minimum and maximum exposure time settings for the VC-25MC-31 I camera are shown in the following table.

Camera Model	Minimum Exposure Time	Maximum Exposure Time [†]
VC-25MC-31 I	1 μs	60,000,000 μs

^{†:} When the **Exposure Mode** is set to **Trigger Width**, the exposure time is controlled by the external trigger signal and has no maximum limit.

Table 8.1 Minimum and Maximum Exposure Time Setting

8.5 Overlapping Exposure with Sensor Readout

The frame acquisition process on the camera includes two distinct parts. The first part is the exposure of the pixels in the image sensor. Once exposure is complete, the second part of the process – readout of the pixel values from the sensor – takes place. In regard to this frame acquisition process, the VC-25MC-31 I camera basically operates with 'overlapped' exposure so that the exposure for a new frame can be overlapped with the sensor readout for the previous frame.

When a new trigger signal is applied to the camera while reading out the previous frame, the camera begins the process of exposing a new frame. This situation is illustrated in the following figure with the **Trigger Mode** set to **On**, the **Trigger Source** set to **Line0** and the **Exposure Mode** set to **Trigger Width**.

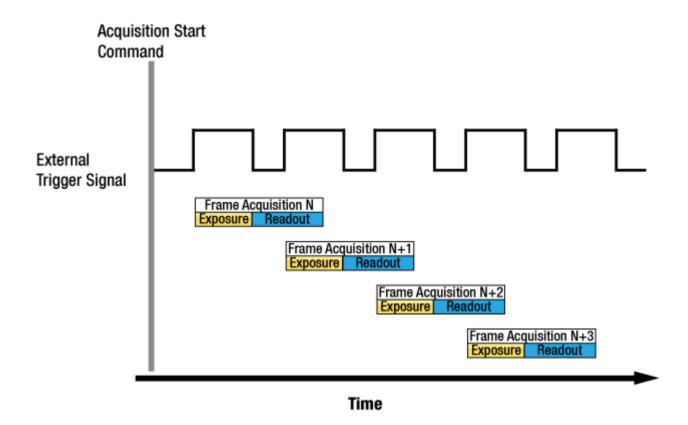


Figure 8.6 Overlapped Exposure and Readout

Determining whether your camera is operating with overlapped exposure and readout is not a matter of issuing a command or changing a setting. Rather a way that you operate the camera will determine whether the exposures and readouts are overlapped or not. If we define the "Frame Period" as the time from the start of exposure for one frame acquisition to the start of exposure for the next frame acquisition, then:

Overlapped: Frame Period ≤ Exposure Time + Readout Time



Guidelines for Overlapped Exposure

Since the VC-25MC-31 I camera operates with overlapped exposure, you must keep in mind two important guidelines:

- You must not begin the exposure for a new frame while the exposure for the previous frame is in progress.
- You must not end the exposure for the current frame until the readout for the previous frame is complete.

When you are operating the camera with overlapped exposure and using an external trigger signal to trigger image acquisition, you could use the camera's Exposure Time parameter settings and timing formula to calculate when it is safe to begin each new acquisition.

8.6 Global Shutter

The VC-25MC-31 I camera is equipped with an image sensor that has an electronic global shutter.

When an exposure start trigger signal is applied to the camera equipped with a global shutter, exposure begins for all lines in the sensor as shown in the figure below. Exposure continues for all lines in the sensor until the programmed exposure time ends or when the exposure start trigger signal ends the exposure time if the camera is using the trigger width exposure mode. At the end of the exposure time, exposure ends for all lines in the sensor. Immediately after the end of exposure, pixel data readout begins and proceeds line by line until all pixel data is read out of the sensor. A main characteristic of a global shutter is that for each frame acquisition, all of the pixels in the sensor start exposing at the same time and all end exposing at the same time. This means that image brightness tends to be more uniform over the entire area of each acquired image, and it helps to minimize problems with acquiring images of object in motion.

The camera can provide an **Exposure Active** output signal that will go high when the exposure time for a frame acquisition begins and will go down when the exposure time ends.

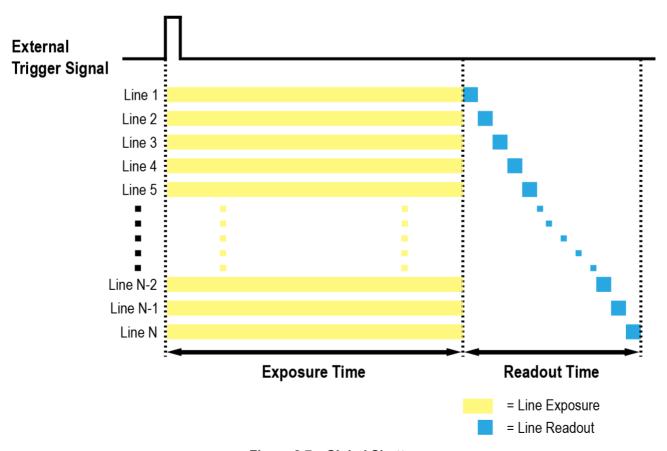


Figure 8.7 Global Shutter

8.7 Maximum Allowed Frame Rate

In general, the maximum allowed acquisition frame rate on the camera may be limited by several factors:

- The amount of time that it takes to transmit an acquired frame from the camera to your computer.

 The amount of time needed to transmit a frame depends on the bandwidth assigned to the camera.
- The amount of time it takes to read an acquired frame out of the image sensor and into the camera's frame buffer. This time varies depending on the setting for ROI. Frames with a smaller height and/or width take less time to read out of the sensor. The frame height and width are determined by the camera's **Height** and **Width** settings in the **Image Format Control** category.
- The Device Tap Geometry. When the camera is set for a Device Tap Geometry that uses more taps, it can
 typically transfer data out of the camera faster than when it is set for a Device Tap Geometry that uses less
 taps.
- The exposure time for acquired frames. If you use very long exposure time, you can acquire fewer frames per second.

8.7.1 Increasing the Maximum Allowed Frame Rate

You may find that you would like to acquire frames at a rate higher than the maximum allowed with the camera's current settings. In this case, you must adjust one or more of the factors that can influence the maximum allowed frame rate and then check to see if the maximum allowed frame rate has increased.

- The time that it takes to transmit a frame out of the camera is the main limiting factor on the frame rate. You can decrease the frame transmission time (and thus increase the maximum allowed frame rate) by using the ROI feature. Decreasing the size of the Image ROI may increase the maximum allowed frame rate. If possible, decrease the height and/or width of the Image ROI.
- If you are using a Device Tap Geometry with a low number of taps, consider using a Device Tap Geometry with a high number of taps. This will usually increase the maximum allowed frame rate.
- If you are using normal exposure times and you are using the camera at its maximum resolution, your exposure time will not normally restrict the frame rate. However, if you are using long exposure time, it is possible that your exposure time is limiting the maximum allowed frame rate. If you are using a long exposure time, try using a shorter exposure time and see if the maximum allowed frame rate increases (You may need to compensate for a lower exposure time by using a brighter light source or increasing the opening of your lens aperture.).



A very long exposure time severely limits the camera's maximum allowed frame rate. As an example, assume that your camera is set to use a 1 second exposure time. In this case, because each frame acquisition will take at least 1 second to be completed, the camera will only be able to acquire a maximum of one frame per second.

9 Camera Features

9.1 Image Region of Interest

The Image Region of Interest (ROI) feature allows you to specify a portion of the sensor array. You can acquire only the frame data from the specified portion of the sensor array while preserving the same quality as you acquire a frame from the entire sensor array.

With the ROI feature, you can increase the maximum allowed frame rate by decreasing the **Width** and/or **Height** parameters. The ROI is referenced to the top left corner [origin (0, 0)] of the sensor array as shown below.

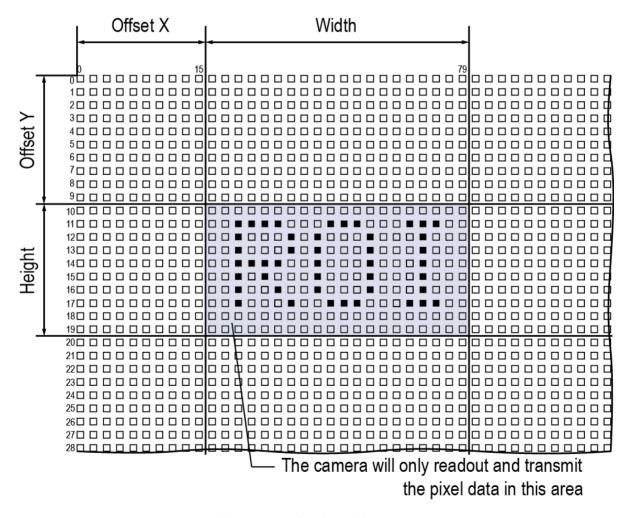


Figure 9.1 Region of Interest



The XML parameters related to ROI settings are as follows.

XML Parameters		Value	Description
	SensorWidtha	-	Effective width of the sensor
	SensorHeighta	-	Effective height of the sensor
	WidthMax		Maximum allowed width of the image with the current
	vvidiliviax	-	camera settings
	ImageFormatControl HeightMax	-	Maximum allowed height of the image with the current
imageromatControl			camera settings
	Width ^b	-	Sets the Width of the Image ROI.
	Height ^b	-	Sets the Height of the Image ROI.
	OffsetX ^c	-	Sets the horizontal offset from the origin to the Image ROI.
	OffsetY c	-	Sets the vertical offset from the origin to the Image ROI.

The unit for all parameters in this table is pixel.

- a: Read only. User cannot change the value.
- b: User configurable parameters for setting ROI
- c: User configurable parameters for setting the origin of the ROI

Table 9.1 XML Parameters related to ROI

You can change the size of ROI by setting the **Width** and **Height** parameters in the **Image Format Control** category. You can also change the position of the ROI origin by setting the **Offset X** and **Offset Y** parameters. Make sure that the **Width + Offset X** value is less than the **Width Max** value, and the **Height + Offset Y** value is less than the **Height Max** value. You must set the size of the ROI first, and then set the Offset values since the **Width** and **Height** parameters are set to its maximum value by default.

• On the VC-25MC-31 I camera, the **Width** parameter must be set to a multiple of 16, and the **Height** parameter must be set to a multiple of 2.

The minimum allowed setting values for the ROI Width and Height are shown below.

Camera Model	Minimum Width Settings	Minimum Height Settings
VC-25MC-31 I	64	2

Table 9.2 Minimum ROI Width and Height Settings



When you change the Image ROI settings after executing the **Acquisition Start** command, the camera may acquire abnormal images. Change the Image ROI settings after executing the **Acquisition Stop** command.



On the VC-25MC-31 I camera, the maximum allowed frame rates depending on Horizontal and Vertical ROI changes are shown below.

ROI Size (H × V)	2 Tap	4 Tap	8 Тар	10 Tap
5120 × 1000	32.0 fps	63.7 fps	126.1 fps	158.5 fps
5120 × 2000	16.2 fps	32.3 fps	64.0 fps	80.4 fps
5120 × 3000	10.8 fps	21.6 fps	42.9 fps	53.9 fps
5120 × 4000	8.1 fps	16.3 fps	32.2 fps	40.5 fps
64 × 5120	31.7 fps	31.7 fps	31.7 fps	31.7 fps
2560 × 5120	12.7 fps	25.7 fps	31.7 fps	31.7 fps
3008 × 5120	10.8 fps	21.7 fps	31.7 fps	31.7 fps
4608 × 5120	7.1 fps	14.2 fps	28.1 fps	31.7 fps
5120 × 5120	6.4 fps	12.7 fps	25.2 fps	31.7 fps

Table 9.3 Maximum Frame Rates by VC-25MC-31 I ROI Changes



Your Camera Link frame grabber may place additional restrictions on how the ROI location and size must be set. Refer to your Camera Link frame grabber user manual for more information.

9.2 Multi-ROI

The VC-25MC-31 I camera provides the Multi-ROI feature which allows you to define up to 16 regions of the sensor array. When an image is acquired, only the pixel information from the defined regions will be readout of the sensor. The pixel data read out of the regions will then be combined together and will be transmitted from the camera as a single image.

The XML parameters related to Multi-ROI are as follows.

XML Pa	rameters	Value	Description
	MultiROISelector		Selects the ROI to set.
	MultiROIMode	On/Off	Enables / Disables the selected ROI.
	MultiROIWidth	-	Width setting for the selected ROI
	MultiROIHeight	-	Height setting for the selected ROI
	MultiROIOffsetX		Horizontal offset from the origin to the selected
	WidthOlonsetX	-	ROI
MultiROIControl	Mark Dolog and		Vertical offset from the origin to the selected
	MultiROIOffsetY	-	ROI
	MultiPOI\/alida		Verifies the validation of the Multi-ROI setting
	MultiROIValid ^a	-	values.
	MultiROIStatus		Displays the status of the Multi ROI feature.
		Active/Inactive	Active: The Multi-ROI feature is in use.
			Inactive: The Multi-ROI is not in use.

The unit for all parameters in this table is pixel.

Table 9.4 XML parameters related to Multi-ROI

a: If the setting values for the Multi-ROI feature are valid, 'True' will be returned or the check box will be selected.



It is recommended that you first set the **Multi-ROI Width** parameter, since all of the regions must be the same width. The next step in the setup process is to define each individual region as desired. Up to 16 regions can be set up ranging from 0 through 15. Use the **Multi-ROI Selector** parameter to select which ROI to set and then set the ROI to On/Off by using the **Multi-ROI Mode** parameter. Then, set the **Multi-ROI Offset X**, **Multi-ROI Offset Y** and **Multi-ROI Height** parameters to define each region.

In the figure below, for example, three regions have been set. With these settings, the camera would output an image as follows:

MultiROI Width × the total height of the three regions (Region0 Height + Region1 Height + Region2 Height)

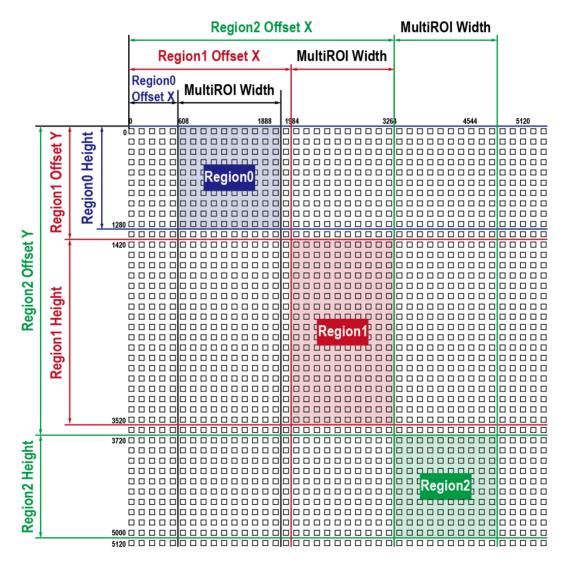


Figure 9.2 Multi-ROI



There are several things to keep in mind when setting the Multi-ROI feature on the VC-25MC-31 I camera:

- The sum of the Multi-ROI Offset X value plus the Multi-ROI Width value must not exceed the width of the camera's sensor.
- The sum of the Multi-ROI Offset Y value plus the Multi-ROI Height value must not exceed the height of the camera's sensor.
- The Multi-ROI Offset X and Multi-ROI Width value must be a multiple of 16.
- The Multi-ROI Offset Y and Multi-ROI Height value must be a multiple of 2.
- You can save the Multi-ROI setting values as a User Set and then load the values to the camera when desired. For more information, refer to <u>9.22 User Set Control</u>.

9.3 Device Tap Geometry

The VC-25MC-31 I camera supports 2 Tap, 4 Tap, 8 Tap and 10 Tap Device Tap Geometry. The number of taps represents the number of pixel data that will be output on each cycle of the Camera Link Pixel Clock. The maximum allowed frame rate will be changed according to the Device Tap Geometry settings. The image data is transmitted in the interleaved order as shown in the figure below.

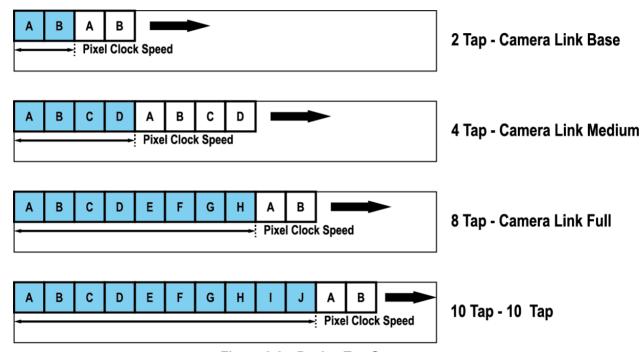


Figure 9.3 Device Tap Geometry

The XML parameter related to Device Tap Geometry is as follows.

XML F	XML Parameters		Description
	DeviceTapGeometry	Geometry_1X2_1Y	Sets the Device Tap Geometry to 2 Tap.
TransportLayer		Geometry_1X4_1Y	Sets the Device Tap Geometry to 4 Tap.
Control		Geometry_1X8_1Y	Sets the Device Tap Geometry to 8 Tap.
		Geometry_1X10_1Y	Sets the Device Tap Geometry to 10 Tap.

Table 9.5 XML Parameter related to Device Tap Geometry

9.4 Pixel Format

The camera processes image data in the unit of 12 bit. You can determine the pixel format (8 bits, 10 bits or 12 bits) of these image data transmitted from the camera by using the **Pixel Format** parameter. When the camera is set for 8-bit or 10-bit pixel format, the four or two least significant bits will be dropped from overall 12 bits.

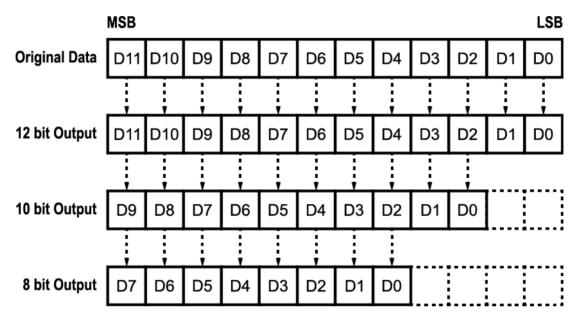


Figure 9.4 Pixel Format

The XML parameter related to Pixel Format is as follows.

XML Parameter		Description
ImageFormatControl	PixelFormat	Sets the pixel format supported by the device.

Table 9.6 XML Parameter related to Pixel Format

The available pixel formats on the monochrome and color cameras are as follows.

	Mono Sensor		Color Sensor
•	Mono 8	•	Mono 8
•	Mono 10	•	Mono 10
•	Mono 12	•	Mono 12
		•	Bayer GB 8
		•	Bayer GB 10
		•	Bayer GB 12

Table 9.7 Pixel Format Values

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9.5 Data ROI (Color Camera)

The Balance White Auto feature provided by the color camera uses the pixel data from a Data Region of Interest (ROI) to adjust the related parameters. The XML parameters related to Data ROI are as follows.

XML Parameters		Value	Description	
	RoiSelector	WhiteBalanceAuto	Selects a Data ROI used for Balance White Auto.	
	Kolselectol	WillebalanceAuto	Only available on the color camera.	
DetaDeiCentral	RoiOffsetX	_	X coordinate of start point ROI	
DataRoiControi	DataRoiControl RoiOffsetY	_	Y coordinate of start point ROI	
	RoiWidth	_	Width of ROI	
	RoiHeight	-	Height of ROI	

Table 9.8 XML Parameters related to Data ROI

Only the pixel data from the area of overlap between the Data ROI and the Image ROI by your settings will be effective if you use the Image ROI and Data ROI at the same time. The effective ROI is determined as shown in the figure below.

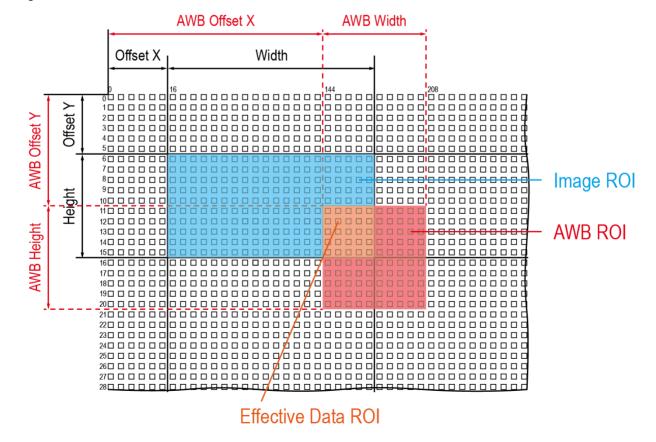


Figure 9.5 Effective Data ROI

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9.6 White Balance (Color Camera)

The color camera includes the white balance capability to adjust the color balance of the images transmitted from the camera. With the white balancing scheme used on the VC-25MC-31 I camera, the Red, Green and Blue intensities can be adjusted individually. You can set the intensity of each color by using the **Balance Ratio** parameter. The Balance Ratio value can range from 1.0 to 4.0. If the **Balance Ratio** parameter is set to 1.0 for a color, the intensity of the color will be unaffected by the white balance mechanism. If the **Balance Ratio** parameter is set to greater than 1.0, the intensity of the color will be proportionally increased to the ratio. For example, if the **Balance Ratio** is set to 1.5, the intensity of that color will be increased by 50%. The XML parameters related to White Balance are as follows.

XML Parameters		Value	Description
	Red	A Balance Ratio value will be applied to red pixels.	
	Polones Datio Colontor	Croon	A Balance Ratio value will be applied to green
AnalogControl	AnalogControl BalanceRatioSelector	Green	pixels.
		Blue	A Balance Ratio value will be applied to blue pixels.
	BalanceRatio	×1.0 ~ ×4.0	Adjusts the ratio of the selected color.

Table 9.9 XML Parameters related to White Balance

9.6.1 Balance White Auto

The Balance White Auto feature is implemented on the color camera. It will control the white balance of the image acquired from the color camera according to the GreyWorld algorithm. Before using the Balance White Auto feature, you need to set the Data ROI for Balance White Auto. If you do not set the related Data ROI, the pixel data from the Image ROI will be used to control the white balance. As soon as the **Balance White Auto** parameter is set to **Once**, the Balance Ratio values for Red and Blue will be automatically adjusted to adjust the white balance by referring to Green. The XML parameters related to Balance White Auto are as follows.

XML Parameter		Value	Description
A La Cartal Balance Military	Off	Balance White Auto Off	
AnalogControl	BalanceWhiteAuto	Once	White Balance is adjusted once and then Off.

Table 9.10 XML Parameter related to Balance White Auto



9.7 Gain and Black Level

Increasing the **Gain** parameter increases all pixel values of the image. This results in a higher grey value output from the camera for a given amount of output from the image sensor.

- 1. Selects the Gain Control (Digital All is only available) to be adjusted by using the Gain Selector parameter.
- 2. Sets the Gain parameter to the desired value.

Adjusting the **Black Level** parameter will result in an offset to the pixel values output from the camera.

- Selects the Black Level Control (Digital All is only available) to be adjusted by using the Black Level Selector parameter.
- 2. Sets the Black Level parameter to the desired value. The available setting range varies depending on the Pixel Format settings.

The XML parameters related to Gain and Black Level are as follows.

XML Parameters		Value	Description
	GainSelector	DigitalAll	Applies the Gain value to all digital channels.
AnalogControl	Gain	1.0× ~ 32.0×	Sets a digital gain value.
AnalogControl	BlackLevelSelector	DigitalAll	Applies the Black Level value to all digital channels.
	BlackLevel	0 ~ 255	Sets a black level value.

Table 9.11 XML Parameters related to Gain and Black Level

9.8 Defective Pixel Correction

The CMOS sensor may have defect pixels which cannot properly react to the light. Correction is required since it may deteriorate the quality of output image. Defect pixel information of CMOS used for each camera is entered into the camera during the manufacturing process. If you want to add defect pixel information, it is required to enter coordinate of new defect pixel into the camera. For more information, refer to Appendix A.

9.8.1 Correction Method

A correction value for a defect pixel is calculated based on the valid pixel value adjacent in the same line.

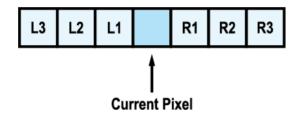


Figure 9.6 Location of Defect Pixel to be corrected

If the Current Pixel is a defect pixel as shown in the figure above, the correction value for this pixel is obtained as shown in the following table depending on whether surrounding pixels are defect pixels or not.

Adjacent Defect Pixel	Correction Value of Current Pixel
None	(L1 + R1) / 2
L1	R1
R1	L1
L1, R1	(L2 + R2) / 2
L1, R1, R2	L2
L2, L1, R1	R2
L2, L1, R1, R2	(L3 + R3) / 2
L2, L1, R1, R2, R3	L3
L3, L2, L1, R1, R2	R3

Table 9.12 Calculation of Defect Pixel Correction Value



9.9 Dark Signal Non-uniformity Correction

In theory, when a digital camera acquires an image in complete darkness, all of the pixel values in the image should be near zero and they should be equal. In practice, however, slight variations in the performance of the pixels in the sensor will cause some variations in the pixel values output from the camera when the camera is acquiring in darkness. This variation is known as Dark Signal Non-Uniformity (DSNU). The VC-25MC-31 I camera provides the DSNU Correction feature.

The XML parameters related to DSNU are as follows.

X	XML Parameters		Description
		Default	Selects Default as a non-volatile memory location to load
	DSNUDataSelector		DSNU data from.
	DSNODataSelector	Space 1 2	Selects a user defined location as a non-volatile memory
		Space1 - 3	location to save DSNU data to or load DSNU data from.
	DSNUDataGenerate	_	Generates the DSNU data for the current camera settings.
	DSNUDataSave	-	Saves the generated DSNU data in the non-volatile memory.
DSNU			The generated data by executing the DSNUDataGenerate
			command are saved in the volatile memory so that the
			data are lost if the camera is reset or if power is turned off.
			To use the data after the camera is powered on or reset,
			save it in the non-volatile memory.
	DSNUDataLoad	_	Loads the DSNU data from the non-volatile memory into the
	DONODalaLoad		volatile memory.

Table 9.13 XML Parameters related to DSNU



9.9.1 Generating and Saving User DSNU Correction Values

To generate and save user-defined DSNU correction values, use the following procedures.



- For optimum DSNU correction values, we recommend that you generate DSNU data after the temperature of the camera housing has been stabilized.
- Before generating DSNU data, set the FFC feature to Off.
- 1. To obtain the optimum DSNU correction values, set the ROI to the actual settings you will be using during normal operation.
- 2. Ensure that the camera will be acquiring images in complete darkness by covering the camera lens, closing the iris in the lens, or darkening the room.
- 3. Begin acquiring images by setting the camera for the Free-Run mode.
- 4. Execute the **DSNU Data Generate** command to generate DSNU data for the current camera settings.
- 5. The generated DSNU correction values will be activated and saved in the camera's volatile memory.
- 6. To save the generated DSNU correction values in the camera's Flash (non-volatile) memory, use the DSNU Data Selector parameter to specify a location to save the DSNU correction values, and then execute the DSNU Data Save command. The previous DSNU values saved in the memory will be overwritten. To disregard the generated DSNU correction values and load the existing values in the Flash memory, use the DSNU Data Selector parameter to select a desired DSNU correction values, and then execute the DSNU Data Load command.



9.10 Photo Response Non-uniformity Correction

In theory, when a digital camera acquires images with the camera viewing a uniform light-colored target in bright light, all of the pixel values in the image should be near the maximum grey value and they should be equal. In practice, however, slight variations in the performance of the pixels in the sensor, variations in the optics, and variations in the lighting will cause some variations in the pixel values output from the camera. This variation is known as Photo Response Non-Uniformity (PRNU). The VC-25MC-31 I camera provides the PRNU correction feature.

The XML parameters related to PRNU are as follows.

	XML Parameters		Description
		Default	Selects Default as a non-volatile memory location to load
	PRNUNUDataSelector		PRNU data from.
	FINIONODataSelector	Space1 - 3	Selects a user defined location as a non-volatile memory
		орасе 1 - 3	location to save PRNU data to or load PRNU data from.
	PRNUDataGenerate -	_	Generates the PRNU data for the current camera settings.
	PRNUDataSave	_	Saves the generated PRNU data in the non-volatile memory.
PRNU			The generated data by executing the
			PRNUDataGenerate command are saved in the volatile
			memory so that the data are lost if the camera is reset or
			if power is turned off. To use the data after the camera is
			powered on or reset, save it in the non-volatile memory.
	PRNUDataLoad		Loads the PRNU data from the non-volatile memory into the
		_	volatile memory.

Table 9.14 XML Parameters related to PRNU

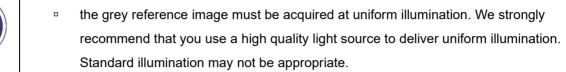


9.10.1 Generating and Saving User PRNU Correction Values

To generate and save user-defined PRNU correction values, use the following procedures.

• To generate the optimum PRNU data,

- we recommend that you generate DSNU correction values first before generating PRNU correction values.
- set the FFC feature to Off before generating PRNU correction values.



- The PRNU correction values stored in Default are optimized for use in typical situations and will provide good camera performance in most cases. Use of the values stored in Default is recommended.
- To generate PRNU correction values suitable for your operating conditions, set the ROI to the actual settings you will be using during normal operation. We strongly recommend that you use the Default PRNU correction values stored in Default, if you cannot set up the uniform illumination.
- 2. Without mounting a lens on the camera, place a uniform illumination (e.g. backlight) in the field of view of the camera. Set up the camera as you would for normal operation. We recommend that you make adjustments to achieve the digital output level in a range from 150 to 200 (Gain: 1.00 at 8 bit).
- 3. Begin acquiring images by setting the camera for the Free-Run mode.
- 4. Execute the **PRNU Data Generate** command to generate PRNU correction values for the current camera settings.
- 5. The generated PRNU correction values will be activated and saved in the camera's volatile memory.
- 6. To save the generated PRNU correction values in the camera's Flash (non-volatile) memory, use the PRNU Data Selector parameter to specify a location to save the PRNU correction values, and then execute the PRNU Data Save command. The previous PRNU values saved in the memory will be overwritten. To disregard the generated PRNU correction values and load the existing values in the Flash memory, use the PRNU Data Selector parameter to select a desired PRNU correction values, and then execute the PRNU Data Load command.

9.11 Flat Field Correction

The Flat Field Correction feature improves the image uniformity when you acquire a non-uniformity image due to external conditions. The Flat Field Correction feature of the VC-25MC-31 I camera can be summarized by the following equation.

```
IC = IR / IF

IC: Level value of corrected image
IR: Level value of original image
IF: Level value of Flat Field data
```

In actual use conditions, generate a Flat Field correction data and then save the data into the non-volatile memory of the camera by following the procedures below.

- Execute the Flat Field Data Generate parameter.
 After executing the Flat Field Data Generate parameter, you must acquire one image to generate the scaled down Flat Field correction data.
- 2. Use the **Flat Field Data Selector** parameter to specify a location to save the generated Flat Field correction data.
- 3. Execute the **Flat Field Data Save** parameter to save the generated Flat Field data into the non-volatile memory. When the scaled down Flat Field data are used for correction, they are expanded and applied with a Bilinear Interpolation as shown in the Figure 9.8.
 - To disregard the generated Flat Field correction data and load the existing Flat Field correction data, execute the **Flat Field Data Load** parameter before executing the **Flat Field Data Save** parameter.
- 4. Set the **Flat Field Correction** parameter to **On** to apply the Flat Field data to the camera.



- It is recommended that you enable the **Defective Pixel Correction** feature before executing the **Flat Field Data Generate** parameter.
- Before executing the Flat Field Data Generate parameter, you must set the camera as follows:
 - OffsetX, Y: 0
 - Width, Height: Maximum values
- After executing the Acquisition Start command, you need to operate the camera with the free-run mode or apply a trigger signal to acquire an image.



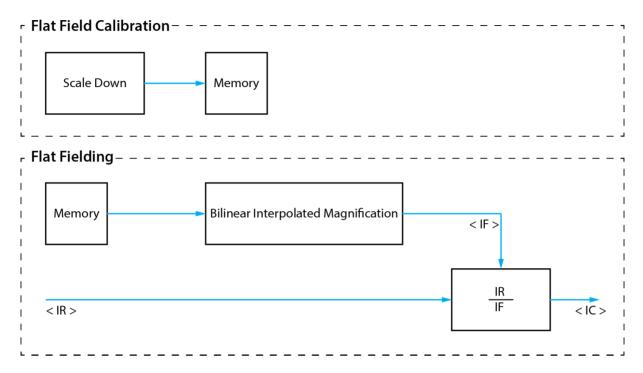


Figure 9.7 Generation and Application of Flat Field Data

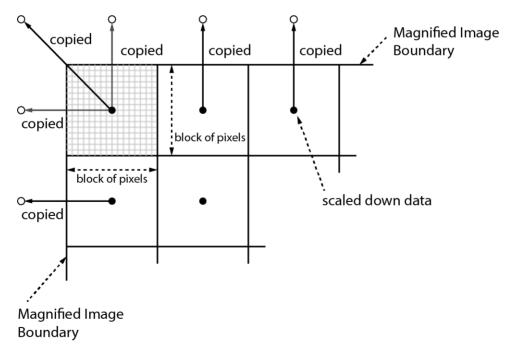


Figure 9.8 Bilinear Interpolated Magnification



The XML parameters related to Flat Field Correction are as follows.

XML	Parameters	Value	Description
	FlatFieldCorrection	Off	Disables the Flat Field Correction feature.
	FlatFleidCollection	On	Enables the Flat Field Correction feature.
			Selects a location to save Flat Field data
	FlatFieldDataSelector	Space0 ~ Space3	to or load Flat Field data from.
	FlatFleidDataSelectol	Spaceo ~ Spaces	Space0~Space3: User defined
			location
	FlatFieldDataGenerate	_	Generates the Flat Field data.
			Saves the generated Flat Field correction
			data in the non-volatile memory.
FlatFieldControl	FlatFieldDataSave	_	The generated data by executing the
			Flat Field Data Generate parameter
			are saved in the volatile memory so
			that the data are lost if the camera is
			reset or if power is turned off. To use
			the data after the camera is powered
			on or reset, save it in the non-volatile
			memory.
	FlatFieldDataLoad	_	Loads the Flat Field data from the non-
	riatrieiuDataLoad	_	volatile memory into volatile memory.

Table 9.15 XML Parameters related to Flat Field Correction



9.11.1 Flat Field Data Selector

As mentioned above, the generated Flat Field correction data is stored in the camera's volatile memory and the data is lost if the camera is reset or powered off. To use the generated Flat Field correction data after the camera is powered on or reset, you need to save it in the camera's non-volatile memory. The VC-25MC-31 I camera provides four reserved locations in the camera's non-volatile memory available for saving and loading the Flat Field correction data. You can use the **Flat Field Data Selector** parameter to select a location as desired.

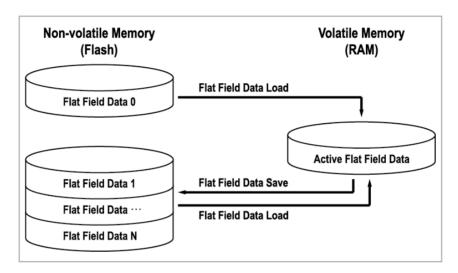


Figure 9.9 Flat Field Data Selector

Saving Flat Field Data

In order to save the active Flat Field data into a reserved location in the camera's Flash memory, follow the procedures below.

- 1. Use the **Flat Field Data Selector** parameter to specify a location to save the active Flat Field data.
- 2. Execute the **Flat Field Data Save** parameter to save the active Flat Field data to the selected location.

Loading Flat Field Data

If you saved a Flat Field correction data into the camera's non-volatile memory, you can load the saved Flat Field correction data from the camera's non-volatile memory into the camera's active Flat Field data location.

- 1. Use the **Flat Field Data Selector** parameter to specify a reserved location whose Flat Field correction data will be loaded into the camera's active Flat Field data location.
- 2. Execute the **Flat Field Data Load** parameter to load the selected Flat Field correction data into the active Flat Field data location.

9.12 Digital I/O Control

The Power Input and Control I/O receptacle of the camera can be operated in various modes.

The XML parameters related to Digital I/O Control are as follows.

XML Pa	XML Parameters		Description
	LineSelector	Line1	Selects the number 4 pin of the camera's Power
	LineSelector	Line	Input and Control I/O receptacle as an output line.
	LineInverter	FALSE	Disables inversion on the output signal of the line.
	Linemverter	TRUE	Enables inversion on the output signal of the line.
		Off	Disables the line output.
		ExposureActive	Outputs pulse signals indicating the current
		ExposureActive	exposure time.
DigitallOControl	LineSource	FrameActive	Outputs pulse signals indicating a frame readout
			time.
		UserOutput0	Outputs pulse signals set by User Output Value.
		Timer0Active	Outputs user-defined Timer signals as pulse signals.
	LloorQutput\/oluo	FALSE	Sets the bit state of the line to Low.
	UserOutputValue -	TRUE	Sets the bit state of the line to High.
	DebounceTime	0 ~ 1,000,000	Sets a Debounce Time in microseconds
		0 ~ 1,000,000	(Default: 0.5 μs).

Table 9.16 XML Parameters related to Digital I/O Control

When you set the Line Source to User Output0, you can use the user setting values as output signals.

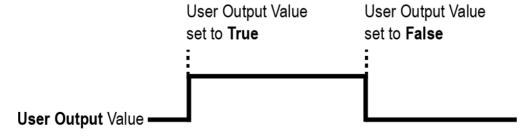


Figure 9.10 User Output

The camera can provide an Exposure Active output signal. The signal goes high when the exposure time for each frame acquisition begins and goes low when the exposure time ends as shown in the figure below. This signal can be used as a flash trigger and is also useful when you are operating a system where either the camera or the object being imaged is movable. Typically, you do not want the camera to move during exposure. You can monitor the Exposure Active signal to know when exposure is taking place and thus know when to avoid moving the camera.

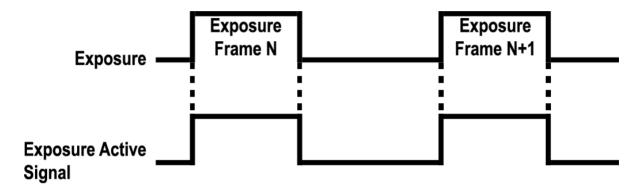


Figure 9.11 Exposure Active Signal

9.12.1 Debounce

The Debounce feature of the VC-25MC-31 I camera allows to supply only valid signals to the camera by discriminating between valid and invalid input signals. The **Debounce Time** parameter specifies the minimum time that an input signal must remain High or Low in order to be considered as a valid input signal. When you use the Debounce feature, be aware that there is a delay between the point where the valid input signal arrives and the point where the signal becomes effective. The duration of the delay is determined by the Debounce Time parameter setting value. When you set the **Debounce Time** parameter, High and Low signals shorter than the setting value are considered invalid and ignored as shown in the figure below.

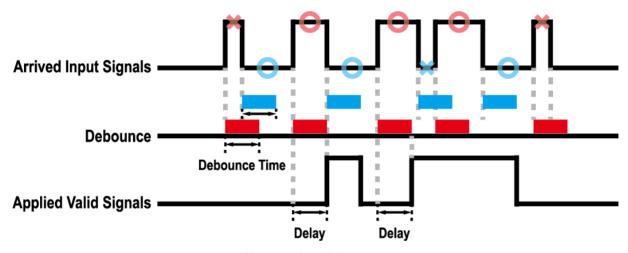


Figure 9.12 Debounce

The XML parameter related to Debounce Time is as follows.

XML Parameters		Value	Description
DigitalIOControl Debounce T	Doboupos Timo	0 4 000 000	Sets a Debounce Time in microseconds
	Debounce Time	0 – 1,000,000 μs	(Default: 0.5 μs).

Table 9.17 XML Parameter related to Debounce Time

9.13 Timer Control

When the **Line Source** parameter is set to **Timer0Active**, the camera can provide output signals by using the Timer. On the VC-25MC-31 I camera, the Frame Active, Exposure Active event or external trigger signal is available as Timer source signal.

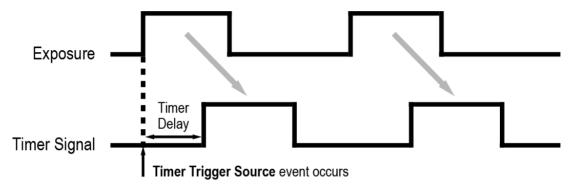
The XML parameter related to Timer are as follows.

XML	Parameters	Value	Description
			Sets the duration of the Timer output signal to
	TimerDuration	0 ~ 60,000,000 μs	be used when Timer Trigger Activation is set
			to Rising/Falling Edge.
	TimerDelay	0 ~ 60,000,000 μs	Sets the delay time to be applied before
	TimorBolay	σ σσ,σσσ,σσσ μ3	starting the Timer.
	TimerReset	-	Resets the Timer and starts it again.
		Off	Disables the Timer trigger.
		Evenesure Active	Sets the Timer to use the current exposure
		ExposureActive	time as the source signal.
	TimerTriggerSource		Sets the Timer to use a frame readout time as
CarratanAnd		FrameActive	the source signal.
CounterAnd		Line0	Sets the Timer to use the external trigger
TimerControl			signal as the source signal.
		RisingEdge	Specifies that a rising edge of the selected
			trigger signal will act as the Timer trigger.
			Specifies that a falling edge of the selected
		FallingEdge	trigger signal will act as the Timer trigger.
	Time a vTui se se se A a tie ca ti a se		Specifies that the Timer output signal will be
	TimerTriggerActivation	LevelHigh	valid as long as the selected trigger signal is
			High.
			Specifies that the Timer output signal will be
		LevelLow	valid as long as the selected trigger signal is
			Low.

Table 9.18 XML Parameters related to Timer Control

For example, when the Timer Trigger Source is set to Exposure Active and the Timer Trigger Activation is set to Level High, the Timer will act as follows:

- 1. When the source signals set by the Timer Trigger Source parameter are applied, the Timer will start operations.
- 2. The delay set by the Timer Delay parameter begins to expire.
- 3. When the delay expires, the Timer signal goes high as long as the source signal is high.



^{*} Timer Trigger Activation is set to Level High.

Figure 9.13 Timer Signal

9.14 Cooling Control

A fan is installed on the rear panel of the camera to radiate heat. You can set the fan to turn on or off. You can also set the fan to turn on when a specified internal temperature is reached.

The XML parameters related to Cooling Control are as follows.

XML Parameters		Value	Description
			Sets the temperature to operate the fan when the
	TargetTemperature	-10℃ ~80℃	FanOperationMode parameter is set to
			Temperature.
		Off	Turns off the fan.
CoolingControl		On	Turns on the fan.
	FanOperationMode	Temperature	Turns on the fan when the internal temperature
			exceeds the value set in the Target Temperature
			parameter.
	FanSpeed	_	Displays the current Fan RPM.

Table 9.19 XML Parameters related to Cooling Control

9.15 Temperature Monitor

The camera has an embedded sensor chip to monitor the internal temperature.

The XML parameters related to Device Temperature are as follows.

XML Parameters		Value	Description
	Dovigo Tomporatura Sala etar	Sensor	Sets a temperature measuring spot to the image sensor.
DeviceControl	DeviceTemperatureSelector	Mainboard	Sets a temperature measuring spot to the mainboard.
	DeviceTemperature	-	Displays device temperature in Celsius.

Table 9.20 XML Parameters related to Device Temperature

9.16 Status LED

A LED is installed on the rear panel of the camera to inform the operation status of the camera. LED status and corresponding camera status are as follows:

Status LED	Description
Steady Red	The camera is not initialized.
Fast Flashing Green	The camera is transmitting image data.

Table 9.21 Status LED

9.17 Test Pattern

To check whether the camera operates normally or not, it can be set to output test patterns generated in the camera, instead of image data from the image sensor. Three types of test patterns are available; image with different value in horizontal direction (Grey Horizontal Ramp), image with different value in diagonal direction (Grey Diagonal Ramp) and moving image with different value in diagonal direction (Grey Diagonal Ramp Moving).

The XML parameter related to Test Pattern is as follows.

XML Parameters		Value	Description
		Off	Disables the Test Pattern feature.
		GreyHorizontalRamp Sets to Grey Horizontal Ramp.	Sets to Grey Horizontal Ramp.
ImagaEarmatCantral	TestPattern	GreyDiagonalRamp	Sets to Grey Diagonal Ramp.
ImageFormatControl	restrattem	GreyDiagonalRampMoving	Sets to Grey Diagonal Ramp Moving.
		Sets to the Test Pattern pro	Sets to the Test Pattern provided by the
		SensorSpecific	image sensor.

Table 9.22 XML Parameters related to Test Pattern

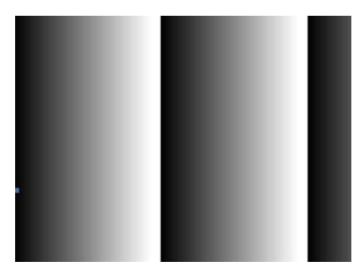


Figure 9.14 Grey Horizontal Ramp

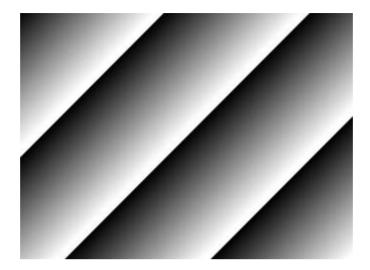


Figure 9.15 Grey Diagonal Ramp

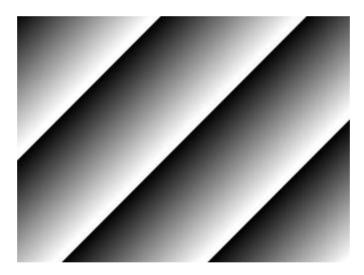


Figure 9.16 Grey Diagonal Ramp Moving



The test pattern may look different because the region of the test pattern may vary depending on the camera's resolution.

9.18 Reverse X

The Reverse X feature lets you flip images horizontally. This feature is available in all operation modes of the camera. The XML parameter related to Reverse X is as follows.

XML Parameters		Value	Description
Imaga Farmat Cantral	DV	FALSE	Disables the Reverse X feature.
ImageFormatControl	ReverseX	TRUE	Flips images horizontally.

Table 9.23 XML Parameter related to Reverse X



Figure 9.17 Original Image

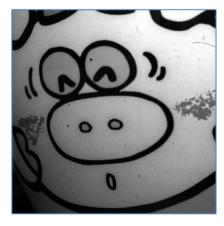


Figure 9.18 Reverse X Image

9.19 Reverse Y

The Reverse Y feature lets you flip images vertically. This feature is available in all operation modes of the camera. The XML parameter related to Reverse Y is as follows.

XML Parameters		Value	Description
ImageFormatControl	D	FALSE	Disables the Reverse Y feature.
	Reverse	TRUE	Flips images vertically.

Table 9.24 XML Parameter related to Reverse Y



Figure 9.19 Original Image



Figure 9.20 Reverse Y Image



- When you use the Reverse Y feature, you must generate the camera's correction data (Defective Pixel Map, DSNU and PRNU) again.
- When the **Pixel Format** parameter is set to **Bayer** and the **Reverse Y** feature is enabled on the color camera, the alignment of the color filter will be changed.

9.20 Device User ID

You can input user defined information up to 16 bytes.

The XML parameter related to Device User ID is as follows.

XML Parameters		Description
DeviceControl	DeviceUserID	Input user defined information (16 bytes).

Table 9.25 XML Parameter related to Device User ID

9.21 Device Reset

Resets the camera physically to power off and on.

The XML parameter related to Device Reset is as follows.

XML Parameters		Description
DeviceControl	DeviceReset	Resets the camera physically.

Table 9.26 XML Parameter related to Device Reset

9.22 Field Upgrade

The camera provides a feature to upgrade the Firmware and FPGA logic through the Camera Link interface rather than disassemble the camera in the field. Refer to Appendix B for more details about how to upgrade.

9.23 User Set Control

You can save the current camera settings to the camera's internal Flash memory. You can also load the camera settings from the camera's internal Flash memory. The camera provides two setups to save and three setups to load settings. The XML parameters related to User Set Control are as follows.

XML Parameters		Value	Description
UserSetControl	UserSetSelector	Default	Selects the Factory Default settings.
		UserSet1	Selects the UserSet1 settings.
		UserSet2	Selects the UserSet2 settings.
	UserSetLoad	-	Loads the User Set specified by User Set Selector
			to the camera.
	UserSetSave	-	Saves the current settings to the User Set
			specified by User Set Selector.
			The Default is a Factory Default Settings and
			allowed to load only.
	UserSetDefault	Default	Applies the Factory Default settings when reset.
		UserSet1	Applies the UserSet1 when reset.
		UserSet2	Applies the UserSet2 when reset.

 Table 9.27
 XML Parameters related to User Set Control

The camera settings stored in the Default can be loaded into the camera's workspace, but cannot be changed. The settings set in the workspace will be lost if the camera is reset or powered off. To use the current setting values in the workspace after a reset, you must save the settings to one of the user spaces.

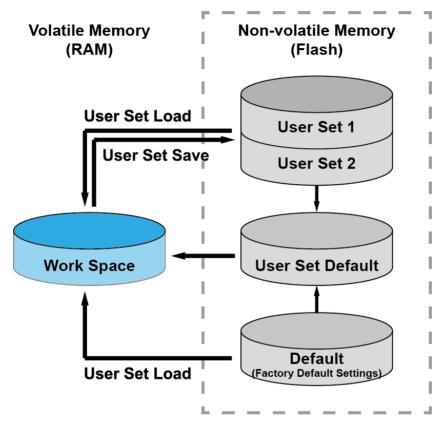


Figure 9.21 User Set Control

10 Camera Configuration

10.1 Serial Communication

You can configure all camera settings via RS-644 serial communication of the Camera Link interface. When you want to control the camera by using a terminal or access directly to the camera by using your application, you need to set your network as follows:

Baud Rate: 1152200 bps

Data Bit: 8 bits
Parity Bit: No parity
Stop Bit: 1 stop bit
Flow Control: None

10.2 Actual Runtime of Parameters

When you change a parameter, the actual runtime of the parameter varies depending on the type of the parameter and the operating status of the camera. All parameters except the Exposure Time parameter are applied to change the camera settings as illustrated below, on the rising edge of a REQ_Frame signal before starting the readout process. When you change the Exposure Time parameter, the exposure time setting will be changed and applied at the starting of the exposure.

If you operate the camera with the Trigger Mode parameter set to On, you must change parameters before applying the trigger signals in order to synchronize image outputs with the parameters.

If you change a parameter in the Free-Run mode, you may acquire up to two images that are not affected by the parameter change. This is true because it is hard to verify the current operating status of the camera in the Free-Run mode.

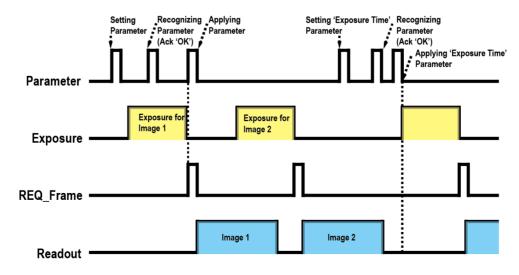


Figure 10.1 Actual Runtime of Parameters

10.3 Configurator

The Configurator, a sample application, is provided to control the VC-25MC-31 I camera. The Configurator allows you to change camera parameters and control the camera.

10.3.1 Starting the Configurator

After connecting the camera to your computer (refer to <u>6 Connecting the Camera</u>), you can run the Configurator by following the procedure below.

- 1. Execute the Configurator.exe file while the camera is powered on. The Camera Scan window appears.
- 2. The Configurator probes if a camera is connected to your computer and then displays the model name of the connected camera in the Camera Scan window.
- Double-click the model name of the camera. The Device Property and Configurator Plus windows appear.
 - The Device Property window displays controls for setting camera parameters.

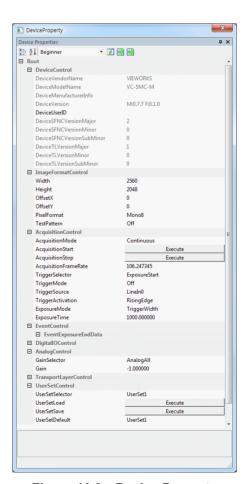


Figure 10.2 Device Property



In the Configurator Plus window, you can display the Device Property window and/or Device
 Maintenance window. In the Device Maintenance window, you can download a Defective Pixel Map or upgrade camera's MCU, FPGA and XML files.

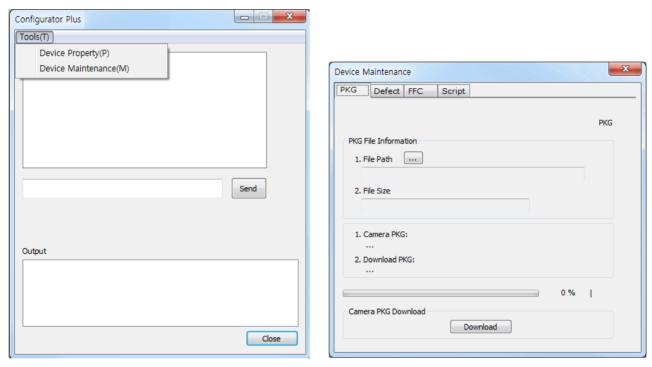


Figure 10.3 Configurator Plus and Device Maintenance

10.4 Command List

You can also use the following commands to set all features provided by the VC-25MC-31 I camera.

Command	Syntax	Return Value	Description
Help	help	String	Displays a list of all commands.
Set ROI Offset X	sox n	ОК	X coordinate of start point ROI
Get ROI Offset X	gox	n	n: X axis offset
Set ROI Offset Y	soy n	ОК	Y coordinate of start point ROI
Get ROI Offset Y	goy	n	n: Y axis offset
Set Image Width	siw n	ОК	Sets a width of the Image ROI.
Get Image Width	giw	n	n: Width value
Set Image Height	sih n	ОК	Sets a height of the Image ROI.
Get Image Height	gih	n	n: Height value
Set Region Selector	srs n	ОК	Selects a ROI to set when setting the Multi-ROI.
Get Region Selector	grs	n	n: Index number of a ROI
			Enables / Disables the selected ROI when
Set Region Mode	src 0 1	ОК	setting the Multi-ROI.
Get Region Mode	grc	0 1	0: Disables the selected ROI.
			1: Enables the selected ROI.
Set Region Offset X	ory n	OK	Sets a horizontal offset from the origin to the
•	srx n	n	selected ROI when setting the Multi-ROI.
Get Region Offset X	grx		n: X axis offset
Cat Dagion Offset V	on/ n	OK	Sets a vertical offset from the origin to the
Set Region Offset Y	sry n	OK n	selected ROI when setting the Multi-ROI.
Get Region Offset Y	gry		n: Y axis offset
Cat Danier Width		OK n	Sets a width for the selected ROI when setting
Set Region Width	srw n		the Multi-ROI.
Get Region Width	grw		n: Width value
Cat Danier Hainkt		OK n	Sets a height for the selected ROI when setting
Set Region Height	srh n		the Multi-ROI.
Get Region Height	grh		n: Height value

Table 10.1 Command List #1



Command	Syntax	Return Value	Description
Set Test Image Get Test Image	sti 0 1 2 3 16 gti	OK 0 1 2 3 16	Sets the Test Image. 0: Disables the Test Image feature. 1: Sets to Grey Horizontal Ramp. 2: Sets to Grey Diagonal Ramp. 3: Sets to Grey Diagonal Ramp Moving. 16: Sets to the Test Image provided by the image sensor.
Set Camera Link Tap Geometry Get Camera Link Tap Geometry	stg 2 4 8 10 gtg	OK 2 4 8 10	Sets the Camera Link Tap Geometry. 2: 1X2-1Y (2 Tap) 4: 1X4-1Y (4 Tap) 8: 1X8-1Y (8 Tap) 10: 1X10-1Y (10 Tap)
Set Data Bit Get Data Bit	sdb 8 10 12 gdb	OK 8 10 12	Sets the Pixel Format. 8: 8 bit 10: 10 bit 12: 12 bit
Set Defect Correction Get Defect Correction	sdc 0 1 gdc	OK 0 1	Sets the Defect Pixel Correction. 0: Disables the Defect Pixel Correction. 1: Enables the Defect Pixel Correction.
Set Horizontal Flip Get Horizontal Flip	shf 0 1 ghf	OK 0 1	Sets the Reverse X (Horizontal Flip). 0: Disables the Reverse X. 1: Enables the Reverse X.
Set Vertical Flip Get Vertical Flip	svf 0 1 gvf	OK 0 1	Sets the Reverse Y (Vertical Flip). 0: Disables the Reverse Y. 1: Enables the Reverse Y.
Acquisition Start Acquisition Stop	ast asp	OK OK	Starts image acquisitions. Stops image acquisitions.

Table 10.2 Command List #2



Command	Syntax	Return Value	Description
Set Frame Rate Get Frame Rate	sfr n gfr	OK n	Sets the rate at which the exposure start trigger will be generated when the Trigger Mode is set to Off.
Get Acquisition Status	gast	0 1	Retrieves the internal acquisition status. 0: The camera is not in the process of acquiring a frame. 1: The camera is in the process of acquiring a frame.
Set Trigger Mode Get Trigger Mode	stm 0 1 gtm	OK 0 1	Sets the Trigger Mode. 0: Trigger Mode Off (Free run mode) 1: Trigger Mode On
Set Trigger Source Get Trigger Source	sts 3 10 14 18 22 gts	OK 3 10 14 18 22	Specifies a source signal when the Trigger Mode is set to On. 3: Software 10: User Output0 14: CC1 18: Timer0 Active 22: Line0
Generate SW Trigger	gst	ОК	Generates a Software trigger signal.
Set Trigger Activation Get Trigger Activation	sta 0 1 gta	OK 0 1	Sets the activation mode for the selected source signal when the Trigger Mode is set to On. 0: Falling Edge 1: Rising Edge
Set Exposure Mode Get Exposure Mode	sem/ses 0 1 gem/ges	OK 0 1	Sets the Exposure Mode. 0: Timed 1: Trigger Width
Set Exposure Time Get Exposure Time	set n get	OK n	Sets an exposure time. n: Exposure time in microseconds (Setting range: 1 – 60,000,000 µs)

Table 10.3 Command List #3



Command	Syntax	Return Value	Description
Set Black Level	sbl n	ОК	Sets the black level value.
Get Black Level	gbl	n	n: Black Level (Setting range: 0 – 255)
Set Digital Gain	sdg n	ОК	Sets the digital gain value.
Get Digital Gain	gdg	n	n: Gain (Setting range: 1× - 32×)
Generate DSNU Data	gdd	ОК	Generates the DSNU data.
Save DSNU Data	sdd	OK	Saves the generated DSNU data in the
Save DSNO Data			non-volatile memory.
Generate PRNU Data	gpd	OK	Generates the PRNU data.
Set PRNU Data Selector	anda 0111212	OK	Selects a PRNU data location.
Get PRNU Data Selector	spds 0 1 2 3		0: Default location
Get PRING Data Selector	gpds	0 1 2 3	1 – 3: User-defined locations
Save PRNU Data	spd	Olí	Saves the generated PRNU correction data
Save PRINU Data		OK	in the selected PRNU data location.
Load PRNU Data	loo d	ОК	Loads the PRNU data from the non-volatile
LOAU PRINO Data	lpd		memory into the volatile memory.
Generate Flat Field Data	gfd	ОК	Executes the Flat Field Generator.
Set Flat Field Data Selector	sfds n	ОК	Selects a Flat Field correction data location.
Get Flat Field Data Selector	gfds	n	n: 0 – 3 (User-defined locations)
Save Flat Field Data	sfd	ОК	Saves the generated Flat Field correction
Save Flat Fleid Data	Siu		data in the selected FFC data location.
Load Flat Field Data	lfd	ОК	Loads the FFC data from the non-volatile
Load Flat Fleid Data			memory into the volatile memory.
Set Flat Field Correction	efe 011	ОК 0 1	Sets the Flat Field Correction feature.
Get Flat Field Correction	sfc 0 1		0: Disables the Flat Field Correction.
Get Flat Fleid Correction	gfc		1: Enables the Flat Field Correction.
			Sets the Fan operation mode.
Set Fan Mode	sfm 0 1 2	ОК	0: Fan Off
Get Fan Mode	gfm	0 1 2	1: Fan On
			2: Temperature

Table 10.4 Command List #4



Command	Syntax	Return Value	Description
Set Target Temperature Get Target Temperature	stt n gtt	OK n	Sets the temperature to operate the fan when the Fan Mode is set to Temperature. n: -10°C - 80°C
Get Fan RPM	gfrpm	String	Displays the Fan RPM.
Set Line Source Get Line Source	sinc 0 4 6 10 18	OK 0 4 6 10 18	Specifies a source signal for the Control I/O receptacle. 0: Off 4: Frame Active
Oct Line Godice	gino	0 4 6 10 18	6: Exposure Active 10: User Output0 18: Timer0 Active
Set Line Inverter Get Line Inverter	slni 0 1 glni	OK 0 1	Sets whether to invert the line output. 0: Disables inversion on the line output. 1: Enables inversion on the line output.
Set User Output Value Get User Output Value	suov 0 1 guov	OK 0 1	Sets the User Output value. 0: Sets the bit state of the line to Low. 1: Sets the bit state of the line to High.
Set Debounce Time Get Debounce Time	sdbt n gdbt	OK n	Sets the Debounce time n: Debounce time in microseconds $(0-1,000,000 \ \mu s)$
Set Timer Duration Get Timer Duration	stdu n gtdu	OK n	Sets the duration of the Timer output signal. n: $1 - 60,000,000 \mu s$
Set Timer Delay Get Timer Delay	stdl n gtdl	OK n	Sets the delay time for the Timer. n: $0-60,000,000~\mu s$
Reset Timer	rtmr	ОК	Resets the Timer and starts it again. Specifies a source signal for the Timer output signal.
Set Timer Trigger Source Get Timer Trigger Source	stts 0 4 6 22 gtts	OK 0 4 6 22	0: Off 4: Frame Active 6: Exposure Active 22: Line0

Table 10.5 Command List #5



Command	Syntax	Return Value	Description
			Sets the activation mode for the Timer.
Cat Timer Trigger Activation	stta 0 1 2 3	OK	0: Falling Edge
Set Timer Trigger Activation		OK	1: Rising Edge
Get Timer Trigger Activation	gtta		2: Level Low
			3: Level High
Set AWB Offset X	swx n	OK	Sets a horizontal offset from the origin to the
Get AWB Offset X	gwx	n	Data ROI.
Set AWB Offset Y	swy n	ОК	Sets a vertical offset from the origin to the
Get AWB Offset Y	gwy	n	Data ROI.
Set AWB Width	sww n	OK	Sets a width for the Data ROI.
Get AWB Width	gww	n	Sets a width for the Data NOI.
Set AWB Height	swh n	ок	Sets a height for the Data ROI.
Get AWB Height	gwh	n	Sets a height for the Data NOI.
Set RGB Gain	srg r g b n	ОК	Sets the intensity of color pixels.
Get RGB Gain	grg r g b n		r g b: Red / Green / Blue pixels
Get NGD Gaill		n	n: Gain value (1.0× ~ 4.0×)
Auto White Balance	arg	OK	Automatically adjusts the white balance once.
Get Model Name	gmn	String	Displays the camera model name.
Get MCU Version	gmv	String	Displays the version of the camera MCU.
Get FPGA Version	gfv	String	Displays the version of the camera FPGA.
Get Serial Number	gsn piece	String	Displays the serial number of the camera.
Get Current Temperature	gct	String	Displays the device temperature in Celsius.
Reset Hardware	rst		Resets the camera physically to power off
Reset Hardware	131	-	and on.

Table 10.6 Command List #6



Command	Syntax	Return Value	Description
			Loads the camera setting values.
Load Config. From	lof 01412	OK 0: Loads the Factory Default Setting. 1: Loads the User 1 Setting. 2: Loads the User 2 Setting.	0: Loads the Factory Default Setting.
	lcf 0 1 2		1: Loads the User 1 Setting.
			2: Loads the User 2 Setting.
			Saves the current camera setting values.
Save Config. To	sct 1 2	ОК	1: Saves to the User 1 Setting.
			2: Saves to the User 2 Setting.
			Specifies setting values to be loaded when reset.
Set Config. Initialization	sci 0 1 2	ОК	0: Factory Default Setting
Get Config. Initialization	gci	0 1 2	1: User 1 Setting
			2: User 2 Setting

Table 10.7 Command List #7

11 Troubleshooting

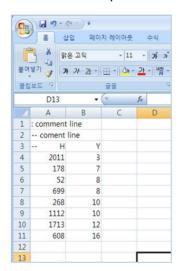
When you have a problem with a Vieworks camera, please check the following:

- · If no image is displayed on your computer,
 - Ensure that all the cable connections are secure.
 - Ensure that the power supply is properly connected.
 - Ensure that trigger signals are applied correctly when you operate the camera with trigger signals.
- · If images are not clear,
 - Ensure the camera lens or glass is clean.
 - Check the lens aperture is adjusted properly.
- If images are dark,
 - Ensure the camera lens is not blocked.
 - Check the exposure time is set properly.
 - Check the aperture is opened properly.
 - Check the Gain value is not set to small.
- If you identify abnormal operation or overheating sign,
 - Ensure the power supply is properly connected.
 - Stop using the camera when you notice smoke or abnormal overheating.
- If you have a problem using the Trigger Mode,
 - Ensure that CC1 settings on your frame grabber are configured correctly when you operate the camera with CC1 trigger signals.
 - Ensure that cable connections are secure when you operate the camera with external trigger signals.
- If there is communication failure between the camera and computer,
 - Ensure that the Camera Link cable connections are secure.
 - Ensure that you have configured a frame grabber in your computer correctly and the camera is connected properly to the frame grabber.

Appendix A Defective Pixel Map Download

1. Create the Defective Pixel Map data in Microsoft Excel format as shown in the left picture below and save as a CSV file (*.csv). The picture in the right shows the created Excel file opened in Notepad. The following rules need to be applied when creating the file.

- Lines beginning with ':' or '—' are treated as notes.
- You must enter the horizontal value first and then vertical value for coordinates of each defect pixel.
- Coordinate values for each pixel can be placed in any order.



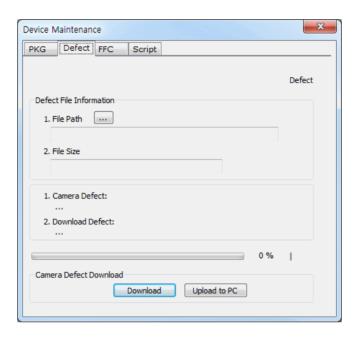


2. Run the Configurator and then select **Tools > Maintenance** in the **Configurator Plus** window.

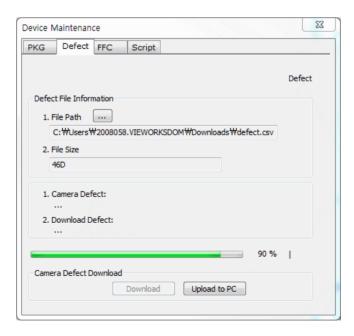




3. In the **Device Maintenance** window, select the **Defect** tab, click the File Path button, search and select the defective pixel map (*.csv), and then click the **Download** button.



4. Once the download is complete, the saving process will begin. During the saving process, make sure not to disconnect the power cord.



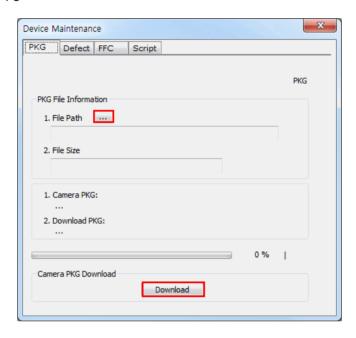
5. After completing the download, click the **OK** button to close the confirmation.



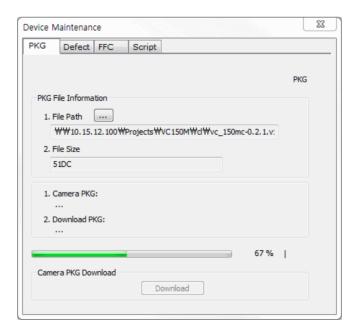
Appendix B Field Upgrade

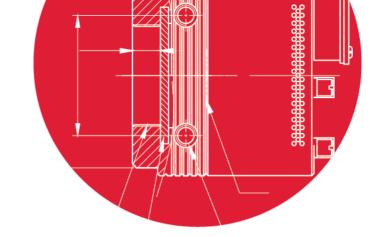
You can upgrade the MCU, FPGA and XML file of the camera by following the procedures below.

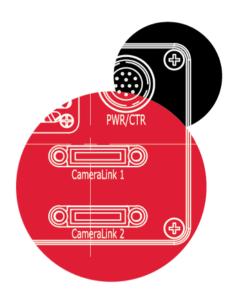
- 1. Run the Configurator and then select **Tools > Device Maintenance** in the **Configurator Plus** window.
- 2. In the **Device Maintenance** window, select the **PKG** tab, click the File Path button, search and select the MCU, FPGA or XML upgrade file, and then click the **Download** button.

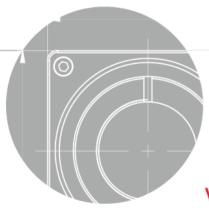


The camera begins downloading the upgrade file and the downloading status is displayed at the bottom of the window.









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